

ESERCIZIO 1

$$\textcircled{1} \quad E_I[\rho] = \int d\bar{r} \rho(\bar{r}) \frac{2C}{3} \sqrt{\rho(\bar{r})}$$

$$\textcircled{2} \quad E[\rho] = \frac{2C}{3} \left[\int d\bar{r} \rho(\bar{r})^{3/2} + \int d\bar{r} \sigma(\bar{r}) \rho(\bar{r}) \right]$$

$$F[\rho] = E[\rho] - \int d\bar{r} \mu \rho(\bar{r})$$

$$\begin{aligned} \mathcal{O} &= \frac{\delta F}{\delta \rho(\bar{r})} = \frac{\delta E}{\delta \rho(\bar{r})} - \mu \\ &= C \sqrt{\rho(\bar{r})} + \sigma(\bar{r}) - \mu \end{aligned}$$

$$\textcircled{3} \quad \boxed{\sqrt{\rho(\bar{r})} = \frac{\mu - \sigma(\bar{r})}{C} \geq 0 \quad (\text{a})}$$

$$\textcircled{4} \quad (\rho + \delta\rho)^{3/2} = \rho^{3/2} \left[1 + \frac{\delta\rho}{\rho} \right]^{3/2}$$

$$\simeq \rho^{3/2} \left[1 + \frac{3}{2} \frac{\delta\rho}{\rho} + \frac{3}{2} \left(\frac{1}{2} \right) \frac{1}{2} \left(\frac{\delta\rho}{\rho} \right)^2 \right]$$

$$\Delta_2 F = \Delta_2 E_I = \frac{2C}{3} \int d\bar{r} \frac{3}{8} \frac{(\delta\rho(\bar{r}))^2}{\sqrt{\rho(\bar{r})}}$$

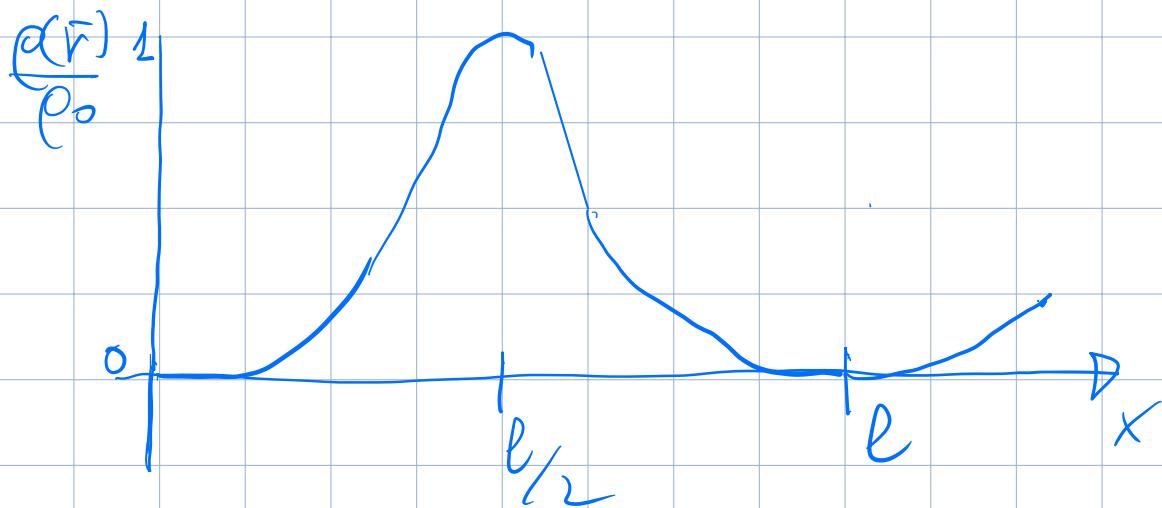
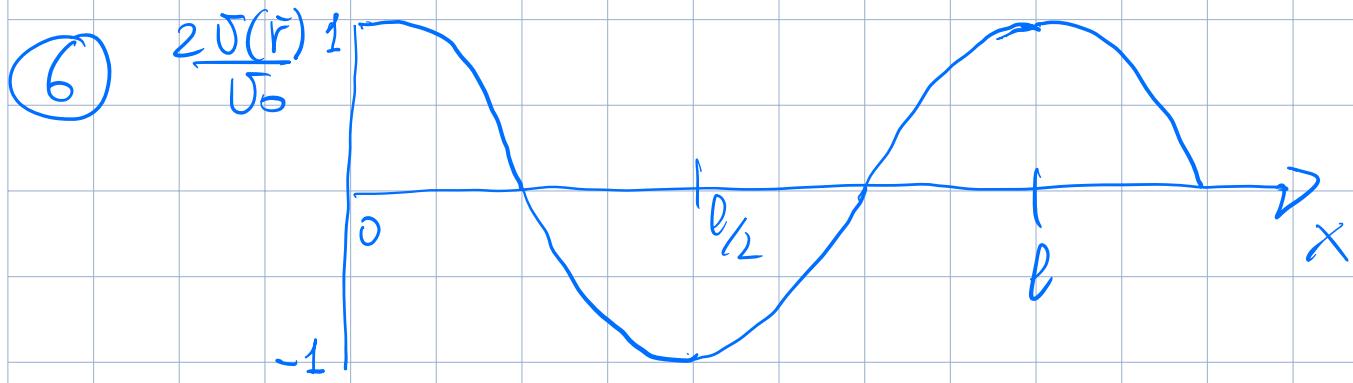
$$\Delta_2 F > 0 \quad \nabla \delta\rho(\bar{r})$$

$$\Rightarrow \frac{C}{\sqrt{\rho(\bar{r})}} = \frac{C^2}{\mu - \sigma(\bar{r})} > 0 \Rightarrow \boxed{\mu - \sigma(\bar{r}) \geq 0 \quad (\text{b})}$$

$$\textcircled{5} \quad \mu - \sigma(r) = \frac{\sigma_0}{2} \left[1 - \cos\left(\frac{2\pi x}{l}\right) \right] = \sigma_0 \sin^2\left(\frac{\pi x}{l}\right)$$

$$P(r) = \left(\frac{\mu - \sigma(r)}{c} \right)^2 = \left(\frac{\sigma_0}{c} \right)^2 \sin^4\left(\frac{\pi x}{l}\right)$$

$$\boxed{P(r) = P_0 \sin^4\left(\frac{\pi x}{l}\right), P_0 = \left(\frac{\sigma_0}{c}\right)^2}$$



ESEMPIO 2

① Fixed β_3 implies

$$\beta_2^2 = 1 - \beta_1^2 - \beta_3^2, \text{ function of } \beta_1 \text{ for given } \beta_3$$

thus

$$m(\bar{\beta}) = \sqrt{\frac{m_1 m_2 m_3}{m_1 \beta_1^2 + (1 - \beta_1^2 - \beta_3^2) m_2 + m_3 \beta_3^2}}$$

$$= \sqrt{\frac{m_1 m_2 m_3}{(m_1 - m_2) \beta_1^2 + (1 - \beta_3^2) m_2 + m_3 \beta_3^2}}$$

Independence on β_1 implies $m_1 - m_2 = 0$

or

$$\boxed{m_1 = m_2 = m_{\text{q1}}}$$

similarly varying β_2 at fixed β_3 implies

$$\beta_1^2 = 1 - \beta_2^2 - \beta_3^2$$

$$m(\bar{\beta}) = \sqrt{\frac{m_1 m_2 m_3}{m_1 (1 - \beta_2^2 - \beta_3^2) + m_2 \beta_2^2 + m_3 \beta_3^2}}$$

$$= \sqrt{\frac{m_1 m_2 m_3}{m_1 (1 - \beta_3^2) + (m_2 - m_1) \beta_2^2 + m_3 \beta_3^2}}$$

The independence on β_2 implies $m_1 = m_2$!

② $\beta_3 = 1 \Rightarrow \beta_1 = \beta_2 = 0$

$$m^* = \sqrt{\frac{m_1 m_2 m_3}{m_3}} = \sqrt{m_1 m_2}$$

$$\approx \sqrt{m_{\pi}^2} = m_{\pi}$$

$$\Rightarrow m_{\pi} = 0.190 \text{ me}$$

③ $\beta_3 = 0 \Rightarrow \beta_2^2 + \beta_1^2 = 1$

$$m^* = \sqrt{\frac{m_1 m_2 m_3}{m_1 \beta_1^2 + m_2 \beta_2^2}} = \sqrt{\frac{m_{\pi}^2 m_3}{m_{\pi} (\beta_1^2 + \beta_2^2)}}$$

$$\approx \sqrt{m_{\pi} m_3} = 0.418 \text{ me}$$

$$\Rightarrow m_3 = \frac{(0.418)^2 \text{ me}^2}{m_{\pi}} - \frac{(0.418)^2}{0.190} \text{ me}$$

$$m_3 \equiv m_L = 0.920 \text{ me}$$

$$(4) C = \frac{\sqrt{2}}{h^3 \pi^2} \sqrt{m_{q_1}^2 m_L} = \frac{\sqrt{2}}{h^3 \pi^2} \sqrt{\frac{m_L m_{q_1}^2}{m_e^3}} m_c^{3/2}$$

$$C = \frac{\sqrt{8}}{(1.05 \cdot 10^{-27})^3 \pi^2} \sqrt{0.920 \cdot (0.19)^2 (9.11 \cdot 10^{-28})^{3/2}}$$

$$= 1.84 \cdot 10^{80} \times 0.182 \times 2.75 \cdot 10^{-41} = 6.21 \cdot 10^{38}$$

$$\boxed{G = 6.21 \cdot 10^{38} \text{ cm}^3 \text{ erg}^{-3/2}}$$

(5) With reference to the lesson on orbits of corner at band extrema in a magnetic field (see material on the course webpage) we have

$$\psi_i = \gamma_i e^{\alpha t}; \quad \alpha = \pm i\omega_c^*, \quad ;$$

$$\omega_c^* = \frac{eH}{m^* c}; \quad \delta = \pm \frac{i}{m^*} .$$

$$\text{since } \vec{\beta} = (0, 1, 0), \quad m^* = \sqrt{\frac{m_L m_{q_1}^2}{m_{q_1}}} = \sqrt{m_L m_\alpha}$$

we get

$$\begin{pmatrix} m_1 \delta & 0 & 1 \\ 0 & m_2 \delta & 0 \\ -1 & 0 & m_3 \delta \end{pmatrix} \begin{pmatrix} \gamma_1 \\ \gamma_2 \\ \gamma_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\delta = 0 \Rightarrow \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix} \begin{pmatrix} \gamma_1 \\ \gamma_2 \\ \gamma_3 \end{pmatrix} = \begin{pmatrix} \gamma_3 \\ 0 \\ -\gamma_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \gamma_2 = (0, 1, 0) \Rightarrow \gamma_y = \text{konstante}$$

$$\delta = \pm \frac{i}{m^*} \Rightarrow \begin{pmatrix} \pm i \frac{m_{Q_1}}{m^*} & 0 & 1 \\ 0 & \pm i \frac{m_{Q_1}}{m^*} & 0 \\ -1 & 0 & \pm i \frac{m_L}{m^*} \end{pmatrix} =$$

$$= \begin{pmatrix} \pm i \sqrt{\frac{m_{Q_1}}{m_L}} & 0 & 1 \\ 0 & \pm i \sqrt{\frac{m_{Q_1}}{m_L}} & 0 \\ -1 & 0 & \pm i \sqrt{\frac{m_L}{m_{Q_1}}} \end{pmatrix} \equiv A$$

$$\Rightarrow A \begin{pmatrix} \gamma_1 \\ \gamma_2 \\ \gamma_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \pm i \sqrt{\frac{m_{Q_1}}{m_L}} \gamma_1 + \gamma_3 \\ \pm i \sqrt{\frac{m_{Q_1}}{m_L}} \gamma_2 \\ -\gamma_1 + \pm i \sqrt{\frac{m_L}{m_{Q_1}}} \gamma_3 \end{pmatrix}$$

$$\Rightarrow \gamma_2 = 0 ; \quad \gamma_3 = \mp i \sqrt{\frac{m_q}{m_L}} \gamma_1$$

$$\bar{r} = \gamma_1 (1, 0, \mp \sqrt{\frac{m_q}{m_L}} i)$$

$$\bar{r}(t) = \operatorname{Re} \left\{ \gamma_1 (1, 0, \mp \sqrt{\frac{m_q}{m_L}} e^{i \frac{\pi}{2}}) e^{\pm i \omega_c^* t} \right\}$$

With γ_1 real we get

$$\bar{r}(t) = \gamma_1 \left(\cos \omega_c^* t, 0, \mp \sqrt{\frac{m_q}{m_L}} \cos \left(\omega_c^* t \pm \frac{\pi}{2} \right) \right)$$

$$\mp \cos \left(\omega_c^* t \pm \frac{\pi}{2} \right) = \sin \omega_c^* t$$

$$\bar{r}(t) = \gamma_1 \left(\cos \omega_c^* t, 0, \sqrt{\frac{m_q}{m_L}} \sin \omega_c^* t \right)$$

$$\bar{r}(t) = \gamma_0 \left(\cos \omega_c^* t, 0, \sqrt{\frac{m_L}{m_q}} \sin \omega_c^* t \right)$$

$$\Delta \bar{r} = \bar{r}(t) - \bar{r}(0) = \frac{\gamma_0}{\omega_c^*} \left(\sin \omega_c^* t, 0, \sqrt{\frac{m_L}{m_q}} \cos \omega_c^* t \right)$$

$$\Delta \bar{r}(t) \quad (\Delta x(t), 0, \Delta z(t))$$

$$\Rightarrow (\Delta x(t))^2 + \frac{m_q}{m_L} (\Delta z(t))^2 = \left(\frac{\gamma_0}{\omega_c^*} \right)^2$$

$$\Rightarrow \frac{(\Delta x(t))^2}{m_\pi} + \frac{(\Delta y(t))^2}{m_L} = \frac{\omega_0^2}{m_\pi \omega_c^{*2}}$$

$$\Rightarrow \boxed{\frac{(\Delta x(t))^2}{\alpha^2} + \frac{(\Delta y(t))^2}{b^2} = 1}$$

$$\alpha^2 = \frac{\omega_0^2}{\omega_c^{*2}}, \quad b^2 = \frac{\omega_0^2}{\frac{m_L}{m_\pi} \omega_c^{*2}}$$

The orbit is an "elliptical" spine.

$$⑥ m^* = \sqrt{\frac{m_\pi^2 m_L}{\frac{1}{3}(2m_\pi + m_L)}} = \sqrt{\frac{3(0.19)^2 0.92}{2 \cdot 0.19 + 0.92} m_e}$$

$$= \sqrt{\frac{0.0996}{1.30}} m_e = 0.277 m_e$$

$$\omega_c^* = \frac{eH}{m^* c} = \frac{4.80 \cdot 10^{-10}}{0.277 \cdot 9.11 \cdot 10^{-28} \cdot 3 \cdot 10^10}$$

$$= \frac{4.80 \cdot 10^{-10}}{7.57 \cdot 10^{-18}} = 6.34 \cdot 10^7 \text{ s}^{-1}$$

$$\kappa_c^* = \frac{\omega_c^*}{c} = 2.11 \cdot 10^{-3} \text{ cm}^{-1}$$