- It is impossible to design an IIR transfer function with an exact linear-phase
- It is always possible to design an FIR transfer function with an exact linear-phase response
- We now develop the forms of the linearphase FIR transfer function H(z) with real impulse response h[n]

As shown below, *h*[*n*] should be either symm. or antisymm.

···→ noncausal IIR system, not realizable

Reminder: Lowpass linear-phase filters can be obtained by truncation and shift of a sinc-shaped impulse response (slide 04.3-54)

• Let
$$H(z) = \sum_{n=0}^{N} h[n]z^{-n}$$

• If H(z) is to have a linear-phase, its frequency response must be of the form

$$H(e^{j\omega}) = e^{j(c\omega+\beta)} \breve{H}(\omega)$$

where c and β are constants, and $H(\omega)$, called the amplitude response, also called the zero-phase response, is a real function of ω

• For a real impulse response, the magnitude response $|H(e^{j\omega})|$ is an even function of ω , i.e.,

$$|H(e^{j\omega})| = |H(e^{-j\omega})|$$

• Since $|H(e^{j\omega})| = |\check{H}(\omega)|$, the amplitude response is then either an even function or an odd function of ω , i.e.

$$\breve{H}(-\omega) = \pm \breve{H}(\omega)$$

• The frequency response satisfies the relation

$$H(e^{j\omega}) = H^*(e^{-j\omega})$$

see DTFT properties table

or, equivalently, the relation

$$e^{j(c\omega+\beta)}\breve{H}(\omega) = e^{-j(-c\omega+\beta)}\breve{H}(-\omega)$$

• If $\breve{H}(\omega)$ is an even function $\breve{H}(-\omega) = \breve{H}(\omega)$, then the above relation leads to

$$e^{j\beta} = e^{-j\beta}$$

implying that either $\beta = 0$ or $\beta = \pi$

• From

$$H(e^{j\omega}) = e^{j(c\omega+\beta)} \breve{H}(\omega)$$

we have

$$\widetilde{H}(\omega) = e^{-j(c\omega+\beta)}H(e^{j\omega})$$

$$= e^{-j\beta} \sum_{n=0}^{N} h[n]e^{-j\omega(c+n)}$$

$$= 0$$

• Replacing ω with $-\omega$ in the previous equation we get

$$\breve{H}(-\omega) = e^{-j\beta} \sum_{\ell=0}^{N} h[\ell] e^{j\omega(c+\ell)}$$

• Making a change of variable $\ell = N - n$, we rewrite the above equation as

$$\widetilde{H}(-\omega) = e^{-j\beta} \sum_{n=0}^{N} h[N-n]e^{j\omega(c+N-n)}$$

- As $\breve{H}(\omega) = \breve{H}(-\omega)$, we have $h[n]e^{-j\omega(c+n)} = h[N-n]e^{j\omega(c+N-n)}$
- For c = -N/2,

$$h[n]e^{-j\omega(-\frac{N}{2}+n)} = h[n]e^{j\omega(\frac{N}{2}-n)}$$

$$h[N-n]e^{j\omega(-\frac{N}{2}+N-n)} = h[N-n]e^{j\omega(\frac{N}{2}-n)}$$

• Equating the right-hand sides of the last two equations we get the condition

$$h[n] = h[N-n], \qquad 0 \le n \le N$$

• Thus, the FIR filter with an even amplitude response will have a linear phase if it has a symmetric impulse response

• Recall that the frequency response of a real coefficient digital filter satisfies the relation

$$H(e^{j\omega}) = H^*(e^{-j\omega})$$

• For a linear-phase FIR filter the above condition is equivalent to

$$e^{j(c\omega+\beta)}\breve{H}(\omega) = e^{-j(-c\omega+\beta)}\breve{H}(-\omega)$$

same as slide 4

• If $\check{H}(\omega)$ is an odd function of ω , then from

$$e^{j(c\omega+\beta)}\breve{H}(\omega) = e^{-j(-c\omega+\beta)}\breve{H}(-\omega)$$

we get $e^{j\beta} = -e^{-j\beta}$ as $\breve{H}(-\omega) = -\breve{H}(\omega)$

- The above is satisfied if $\beta = \pi/2$ or $\beta = -\pi/2$
- From

$$H(e^{j\omega}) = e^{j(c\omega+\beta)} \breve{H}(\omega)$$

$$\breve{H}(\omega) = e^{-j(c\omega + \beta)} H(e^{j\omega})$$

We rewrite the last equation as

$$\widetilde{H}(\omega) = e^{-j(c\omega+\beta)} \sum_{n=0}^{N} h[n]e^{-j\omega n}$$

$$= e^{-j\beta} \sum_{n=0}^{N} h[n]e^{-j\omega(c+n)}$$

$$= e^{-j\beta} \sum_{n=0}^{N} h[n]e^{-j\omega(c+n)}$$

From the above equation we have

$$\widetilde{H}(-\omega) = e^{-j\beta} \sum_{n=0}^{N} h[n] e^{j\omega(c+n)}$$

• If $H(\omega)$ is an odd function of ω , then

$$\breve{H}(-\omega) = -\breve{H}(\omega) = -e^{-j\beta} \sum_{\ell=0}^{N} h[\ell] e^{-j\omega(c+\ell)}$$

$$= -e^{-j\beta} \sum_{n=0}^{N} h[N-n] e^{-j\omega(c+N-n)}$$

$$= 0$$

From the previous slide we have

$$\breve{H}(-\omega) = e^{-j\beta} \sum_{n=0}^{N} h[n] e^{j\omega(c+n)}$$

• Equating the right-hand sides of the two equations in the previous slide we get

$$\sum_{n=0}^{N} h[n]e^{j\omega(c+n)} = -\sum_{n=0}^{N} h[N-n]e^{-j\omega(c+N-n)}$$

• For c = -N/2, the above equation reduces to

$$\sum_{n=0}^{N} h[n]e^{j\omega(-\frac{N}{2}+n)} = -\sum_{n=0}^{N} h[N-n]e^{-j\omega(-\frac{N}{2}+N-n)}$$

$$= -\sum_{n=0}^{N} h[N-n]e^{-j\omega(-\frac{N}{2}+N-n)}$$

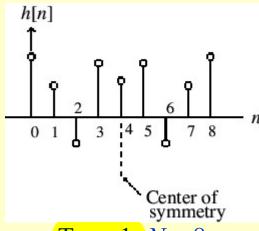
$$\Rightarrow \sum_{n=0}^{N} h[n]e^{-j\omega(\frac{N}{2}-n)} = -\sum_{n=0}^{N} h[N-n]e^{-j\omega(\frac{N}{2}-n)}$$

- Hence, $h[n] = -h[N-n], \quad 0 \le n \le N$
- Therefore, a FIR filter with an odd amplitude response will have linear-phase response if it has an antisymmetric impulse response

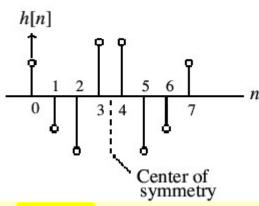
- Since the length of the impulse response can be either even or odd, we can define four types of linear-phase FIR transfer functions
- For an antisymmetric FIR filter of odd length, i.e., *N* even

$$h[N/2] = 0$$

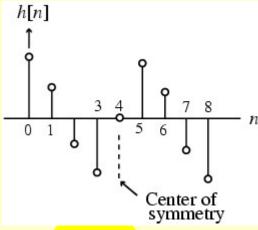
• We examine next the each of the 4 cases



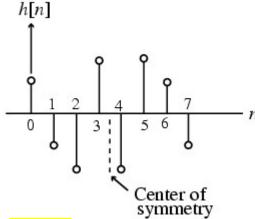
Type 1: N = 8



Type 2: N = 7



Type 3: N = 8



Type 4: N = 7

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Type 1: Symmetric Impulse Response with Odd Length

- In this case, the degree N is even
- Assume N = 8 for simplicity
- The transfer function H(z) is given by

$$H(z) = h[0] + h[1]z^{-1} + h[2]z^{-2} + h[3]z^{-3}$$

+ $h[4]z^{-4} + h[5]z^{-5} + h[6]z^{-6} + h[7]z^{-7} + h[8]z^{-8}$

- Because of symmetry, we have h[0] = h[8], h[1] = h[7], h[2] = h[6], and h[3] = h[5]
- Thus, we can write

$$H(z) = h[0](1+z^{-8}) + h[1](z^{-1}+z^{-7})$$

$$+ h[2](z^{-2}+z^{-6}) + h[3](z^{-3}+z^{-5}) + h[4]z^{-4}$$

$$= z^{-4}\{h[0](z^{4}+z^{-4}) + h[1](z^{3}+z^{-3})$$

$$+ h[2](z^{2}+z^{-2}) + h[3](z+z^{-1}) + h[4]\}$$

• The corresponding frequency response is then given by

$$H(e^{j\omega}) = e^{-j4\omega} \{2h[0]\cos(4\omega) + 2h[1]\cos(3\omega) + 2h[2]\cos(2\omega) + 2h[3]\cos(\omega) + h[4]\}$$

• The quantity inside the braces is a real function of ω , and can assume positive or negative values in the range $0 \le |\omega| \le \pi$

• The phase function here is given by

$$\theta(\omega) = -4\omega + \beta$$

where β is either 0 or π , and hence, it is a linear function of ω

• The group delay is given by

$$\tau(\omega) = -\frac{d\theta(\omega)}{d\omega} = 4$$

indicating a constant group delay of 4 samples

• In the general case for Type 1 FIR filters, the frequency response is of the form

$$H(e^{j\omega}) = e^{-jN\omega/2} \breve{H}(\omega)$$

where the **amplitude response** $\breve{H}(\omega)$, also called the **zero-phase response**, is of the form

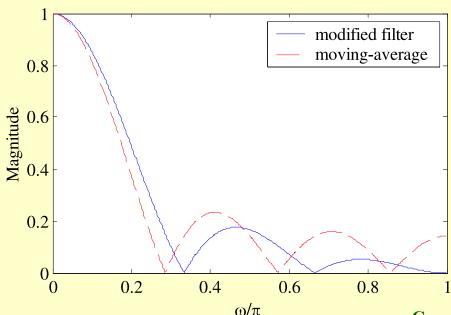
$$\breve{H}(\omega) = h\left[\frac{N}{2}\right] + 2\sum_{n=1}^{N/2} h\left[\frac{N}{2} - n\right] \cos(\omega n)$$

• Example - Consider

$$H_0(z) = \frac{1}{6} \left[\frac{1}{2} + z^{-1} + z^{-2} + z^{-3} + z^{-4} + z^{-5} + \frac{1}{2} z^{-6} \right]$$
which is seen to be a slightly modified version of a length-7 moving-average FIR filter

• The above transfer function has a symmetric impulse response and therefore a linear phase response

• A plot of the magnitude response of $H_0(z)$ along with that of the 7-point moving-average filter is shown below



- Note the improved magnitude response obtained by simply changing the first and the last impulse response coefficients of a moving-average (MA) filter
- It can be shown that we an express

$$H_0(z) = \frac{1}{2}(1+z^{-1}) \cdot \frac{1}{6}(1+z^{-1}+z^{-2}+z^{-3}+z^{-4}+z^{-5})$$

which is seen to be a cascade of a 2-point MA filter with a 6-point MA filter

• Thus, $H_0(z)$ has a double zero at z=-1, i.e., $(\omega = \pi)$

Type 2: Symmetric Impulse Response with Even Length

- In this case, the degree N is odd
- Assume N = 7 for simplicity
- The transfer function is of the form

$$H(z) = h[0] + h[1]z^{-1} + h[2]z^{-2} + h[3]z^{-3} + h[4]z^{-4} + h[5]z^{-5} + h[6]z^{-6} + h[7]z^{-7}$$

• Making use of the symmetry of the impulse response coefficients, the transfer function can be written as

$$H(z) = h[0](1+z^{-7}) + h[1](z^{-1}+z^{-6})$$

$$+ h[2](z^{-2}+z^{-5}) + h[3](z^{-3}+z^{-4})$$

$$= z^{-7/2} \{h[0](z^{7/2}+z^{-7/2}) + h[1](z^{5/2}+z^{-5/2})$$

$$+ h[2](z^{3/2}+z^{-3/2}) + h[3](z^{1/2}+z^{-1/2})\}$$

• The corresponding frequency response is given by

$$H(e^{j\omega}) = e^{-j7\omega/2} \left\{ 2h[0]\cos(\frac{7\omega}{2}) + 2h[1]\cos(\frac{5\omega}{2}) + 2h[2]\cos(\frac{3\omega}{2}) + 2h[3]\cos(\frac{\omega}{2}) \right\}$$

• As before, the quantity inside the braces is a real function of ω , and can assume positive or negative values in the range $0 \le |\omega| \le \pi$

Here the phase function is given by

$$\theta(\omega) = -\frac{7}{2}\omega + \beta$$

where again β is either 0 or π

- As a result, the phase is also a linear function of ω
- The corresponding group delay is

$$\tau(\omega) = \frac{7}{2}$$

indicating a group delay of $\frac{7}{2}$ samples

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• The expression for the frequency response in the general case for Type 2 FIR filters is of the form

$$H(e^{j\omega}) = e^{-jN\omega/2} \breve{H}(\omega)$$

where the amplitude response is given by

$$\breve{H}(\omega) = 2 \sum_{n=1}^{(N+1)/2} h \left[\frac{N+1}{2} - n \right] \cos(\omega (n - \frac{1}{2}))$$

Type 3: Antisymmetric Impulse Response with Odd Length

- In this case, the degree N is even
- Assume N = 8 for simplicity
- Applying the symmetry condition we get

$$H(z) = z^{-4} \{ h[0](z^4 - z^{-4}) + h[1](z^3 - z^{-3}) + h[2](z^2 - z^{-2}) + h[3](z - z^{-1}) \}$$

• The corresponding frequency response is given by

$$H(e^{j\omega}) = e^{-j4\omega} e^{j\pi/2} \{2h[0]\sin(4\omega) + 2h[1]\sin(3\omega) + 2h[2]\sin(2\omega) + 2h[3]\sin(\omega)\}$$

• It also exhibits a linear phase response given by

$$\theta(\omega) = -4\omega + \frac{\pi}{2} + \beta$$

where β is either 0 or π

• The group delay here is

$$\tau(\omega) = 4$$

indicating a constant group delay of 4 samples

• In the general case

$$H(e^{j\omega}) = je^{-jN\omega/2}\breve{H}(\omega)$$

where the amplitude response is of the form

$$\breve{H}(\omega) = 2\sum_{n=1}^{N/2} h\left[\frac{N}{2} - n\right] \sin(\omega n)$$

Type 4: Antisymmetric Impulse Response with Even Length

- In this case, the degree N is odd
- Assume N = 7 for simplicity
- Applying the symmetry condition we get

$$H(z) = z^{-7/2} \{ h[0](z^{7/2} - z^{-7/2}) + h[1](z^{5/2} - z^{-5/2}) + h[2](z^{3/2} - z^{-3/2}) + h[3](z^{1/2} - z^{-1/2}) \}$$

• The corresponding frequency response is given by

$$H(e^{j\omega}) = e^{-j7\omega/2} e^{j\pi/2} \{2h[0]\sin(\frac{7\omega}{2}) + 2h[1]\sin(\frac{5\omega}{2}) + 2h[2]\sin(\frac{3\omega}{2}) + 2h[3]\sin(\frac{\omega}{2})\}$$

• It again exhibits a linear phase response given by

$$\theta(\omega) = -\frac{7}{2}\omega + \frac{\pi}{2} + \beta$$

where β is either 0 or π

• The group delay is constant and is given by

$$\tau(\omega) = \frac{7}{2}$$

In the general case we have

$$H(e^{j\omega}) = je^{-jN\omega/2}\breve{H}(\omega)$$

where now the amplitude response is of the form

$$\breve{H}(\omega) = 2 \sum_{n=1}^{(N+1)/2} h \left[\frac{N+1}{2} - n \right] \sin(\omega(n - \frac{1}{2}))$$

General Form of Frequency Response

• In each of the four types of linear-phase FIR filters, the frequency response is of the form

$$H(e^{j\omega}) = e^{-jN\omega/2}e^{j\beta}\breve{H}(\omega)$$

• The amplitude response $\check{H}(\omega)$ for each of the four types of linear-phase FIR filters can become negative over certain frequency ranges, typically in the stopband

Linear-Phase FIR Transfer Functions

• The magnitude and phase responses of the linear-phase FIR are given by

$$|H(e^{j\omega})| = |\breve{H}(\omega)|$$

$$\theta(\omega) = \begin{cases} -\frac{N\omega}{2} + \beta, & \text{for } \breve{H}(\omega) \ge 0\\ -\frac{N\omega}{2} + \beta - \pi, & \text{for } \breve{H}(\omega) < 0 \end{cases}$$

Linear-Phase FIR Transfer Functions

• The group delay in each case is

$$\tau(\omega) = \frac{N}{2}$$

• Note that, even though the group delay is constant, since in general $|H(e^{j\omega})|$ is not a constant, the output waveform is not a replica of the input waveform

Linear-Phase FIR Transfer Functions

• An FIR filter with a frequency response that is a real function of ω is often called a zerophase filter

• Such a filter must have a noncausal impulse response

- Consider first an FIR filter with a symmetric impulse response: h[n] = h[N-n]
- Its transfer function can be written as

$$H(z) = \sum_{n=0}^{N} h[n]z^{-n} = \sum_{n=0}^{N} h[N-n]z^{-n}$$

• By making a change of variable m = N - n, we can write

$$\sum_{n=0}^{N} h[N-n]z^{-n} = \sum_{m=0}^{N} h[m]z^{-N+m} = z^{-N} \sum_{m=0}^{N} h[m]z^{m}$$
46 $n=0$ $m=0$ $m=0$ Copyright © 2010, S. K. Mitra

• But,

$$\sum_{m=0}^{N} h[m] z^{m} = H(z^{-1})$$

• Hence for an FIR filter with a symmetric impulse response of length *N*+1 we have

$$H(z) = z^{-N}H(z^{-1})$$

A real-coefficient polynomial H(z) satisfying the above condition is called a mirror-image polynomial (MIP)

• Example – A 5th-order mirror-image polynomial

$$H(z) = a_0 + a_1 z^{-1} + a_2 z^{-2} + a_2 z^{-3} + a_1 z^{-4} + a_0 z^{-5}$$

• Note: $z^{-5}H(z^{-1})$ = $z^{-5}(a_0 + a_1z + a_2z^2 + a_2z^3 + a_1z^4 + a_0z^5)$ = $a_0 + a_1z^{-1} + a_2z^{-2} + a_2z^{-3} + a_1z^{-4} + a_0z^{-5}$ = H(z)

• Now consider an FIR filter with an antisymmetric impulse response:

$$h[n] = -h[N-n]$$

• Its transfer function can be written as

$$H(z) = \sum_{n=0}^{N} h[n]z^{-n} = -\sum_{n=0}^{N} h[N-n]z^{-n}$$

• By making a change of variable m = N - n, we get

• Hence, the transfer function H(z) of an FIR filter with an antisymmetric impulse response satisfies the condition

$$H(z) = -z^{-N}H(z^{-1})$$

• A real-coefficient polynomial H(z) satisfying the above condition is called a **antimirror-image polynomial** (AIP)

• Example – A 5th-order antimirror-image polynomial

$$H(z) = a_0 + a_1 z^{-1} + a_2 z^{-2} - a_2 z^{-3} - a_1 z^{-4} - a_0 z^{-5}$$

• Note $-z^{-5}H(z^{-1})$ $= -z^{-5}(a_0 + a_1z + a_2z^2 - a_2z^3 - a_1z^4 - a_0z^5)$ $= a_0 + a_1z^{-1} + a_2z^{-2} - a_2z^{-3} - a_1z^{-4} - a_0z^{-5}$ = H(z)

- It follows from the relation $H(z) = \pm z^{-N} H(z^{-1})$ that if $z = \xi_o$ is a zero of H(z), so is $z = 1/\xi_o$
- Moreover, for an FIR filter with a real impulse response, the zeros of H(z) occur in complex conjugate pairs
- Hence, a zero at $z = \xi_o$ is associated with a zero at $z = \xi_o^*$

• Thus, a complex zero that is not on the unit circle is associated with a set of 4 zeros given by $z = re^{\pm j\phi}$, $z = \frac{1}{r}e^{\pm j\phi}$

• A zero on the unit circle appear as a pair

$$z = e^{\pm j\phi}$$

as its reciprocal is also its complex conjugate

• A real zero inside the unit circle appears with its reciprocal outside the unit circle

$$z = \alpha$$
, $z = \frac{1}{\alpha}$

Constraints on some zero locations

of Linear-

Phase FIR Transfer Functions

- Since a zero at $z = \pm 1$ is its own reciprocal, it can appear only singly
- Now a Type 2 FIR filter satisfies

$$H(z) = z^{-N}H(z^{-1})$$

with degree N odd

• Hence $H(-1) = (-1)^{-N} H(-1) = -H(-1)$ implying H(-1) = 0, i.e., H(z) must have a zero at z = -1

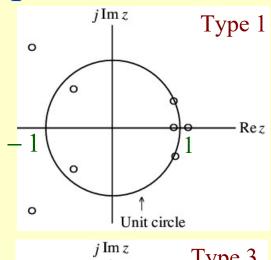
• Likewise, a Type 3 or 4 FIR filter satisfies

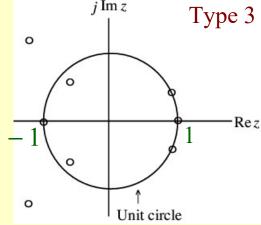
$$H(z) = -z^{-N}H(z^{-1})$$

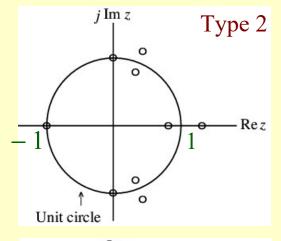
- Thus $H(1) = -(1)^{-N} H(1) = -H(1)$ implying that H(z) must have a zero at z = 1
- On the other hand, only the Type 3 FIR filter is restricted to have a zero at z = -1 since here the degree N is even and hence,

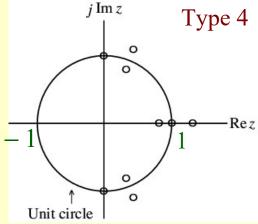
$$H(-1) = -(-1)^{-N} H(-1) = -H(-1)$$

Typical zero locations shown below









- Summarizing
 - (1) Type 1 FIR filter: Either an even number or no zeros at z = 1 and z = -1
 - (2) Type 2 FIR filter: Either an even number or no zeros at z = 1, and an odd number of zeros at z = -1
 - (3) Type 3 FIR filter: An odd number of zeros at z = 1 and z = -1

(4) Type 4 FIR filter: An odd number of zeros at z = 1, and either an even number or no zeros at z = -1

F	ilter Type	No. of zeros at $z = 1$	No. of zeros at $z=-1$	
-	1	Even number or none	Even number or none	
	2	Even number or none	Odd number	
	3	Odd number	Odd number	
	4	Odd number	Even number or none	

Type 1	Type 2	Type 3	Type 4
No restriction Can design any type	Cannot design highpass and bandstop Zero at $\omega = \pi$	Cannot design lowpass, highpass, and bandstop Zero at $\omega = 0$ and $\omega = \pi$	Cannot design lowpass, and bandstop Zero at $\omega = 0$