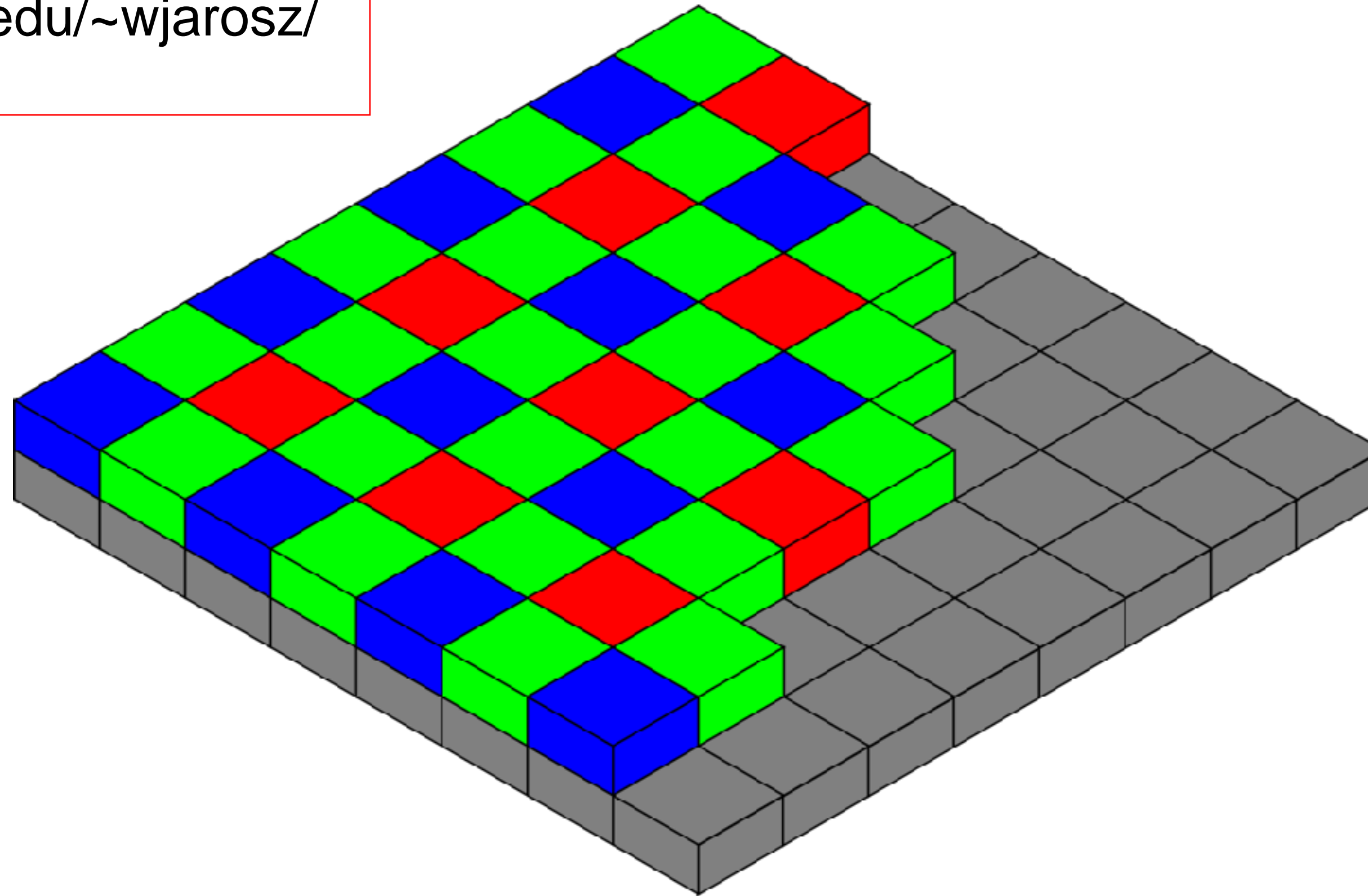


CS 73/273

COMPUTATIONAL PHOTOGRAPHY


<https://cs.dartmouth.edu/~wjarosz/>
Fall 2020



Sensors & Demosaicing

Wojciech Jarosz

wojciech.k.jarosz@dartmouth.edu

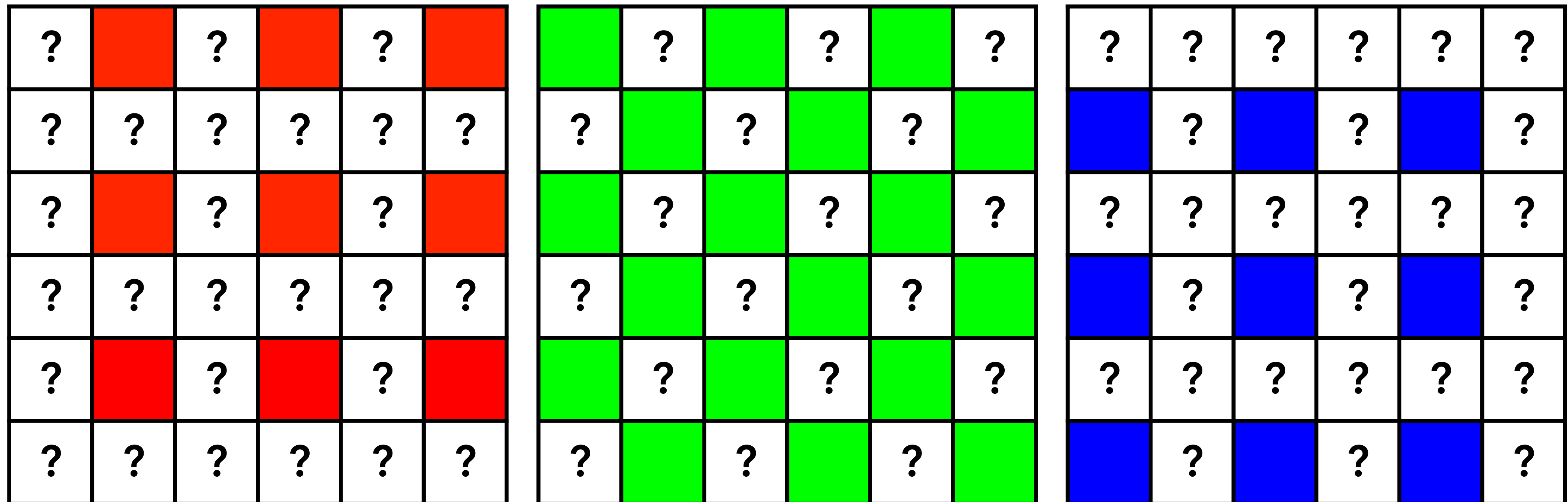


Demosaicing

Demosaicing

Interpolate missing values

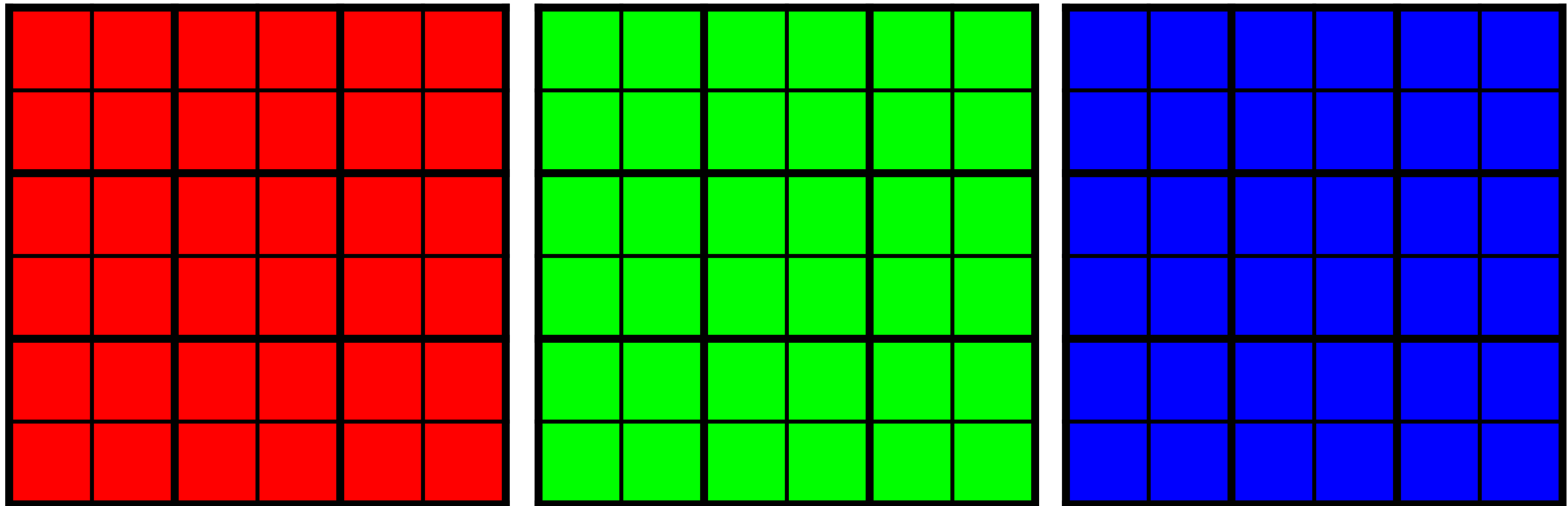
- 2/3 of the full-resolution data will be made up!



Half-resolution demosaicing

Simplest solution: treat each block of 2x2 as a pixel

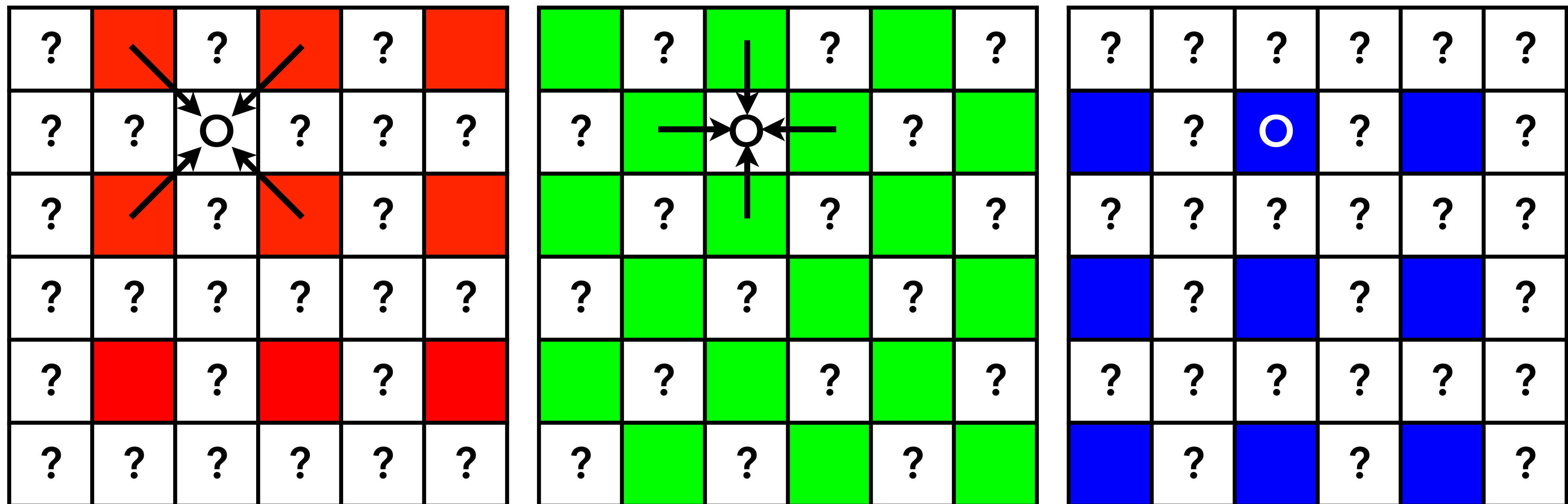
- **Problem 1:** resolution loss (megapixels so important for marketing!)
- **Problem 2:** produces subpixel shifts in color planes!



Centered half-resolution

Average pixels in groups that all have the same "center of gravity"

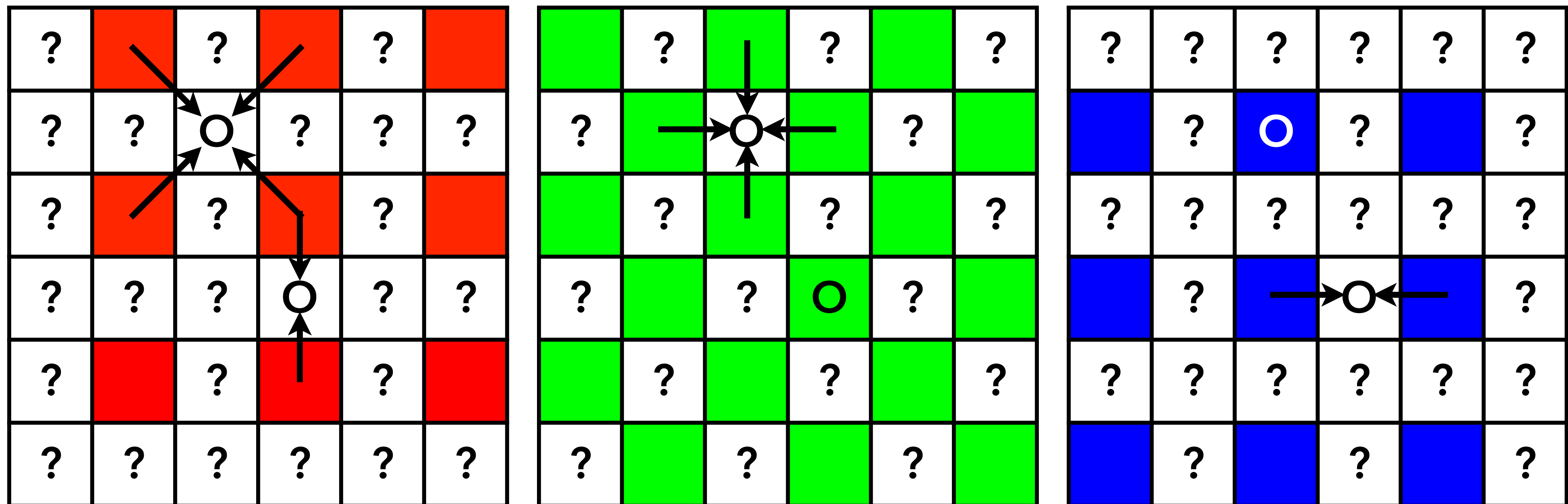
- avoids major color fringing



Linear interpolation

Average pixels in groups that all have the same "center of gravity"

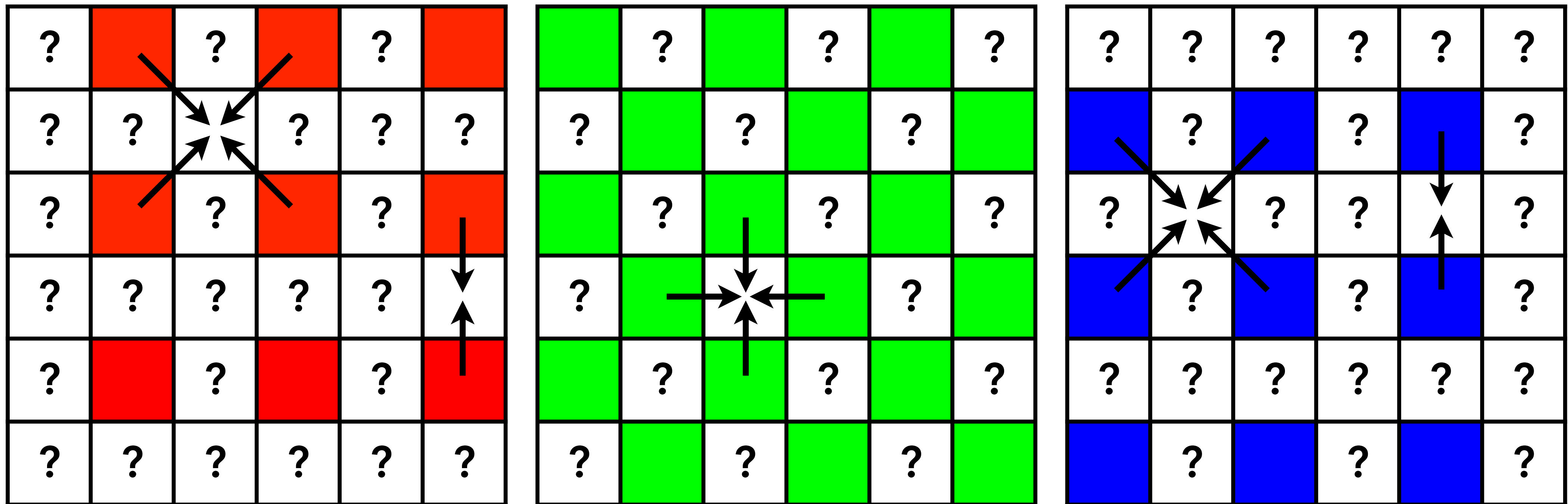
- avoids major color fringing



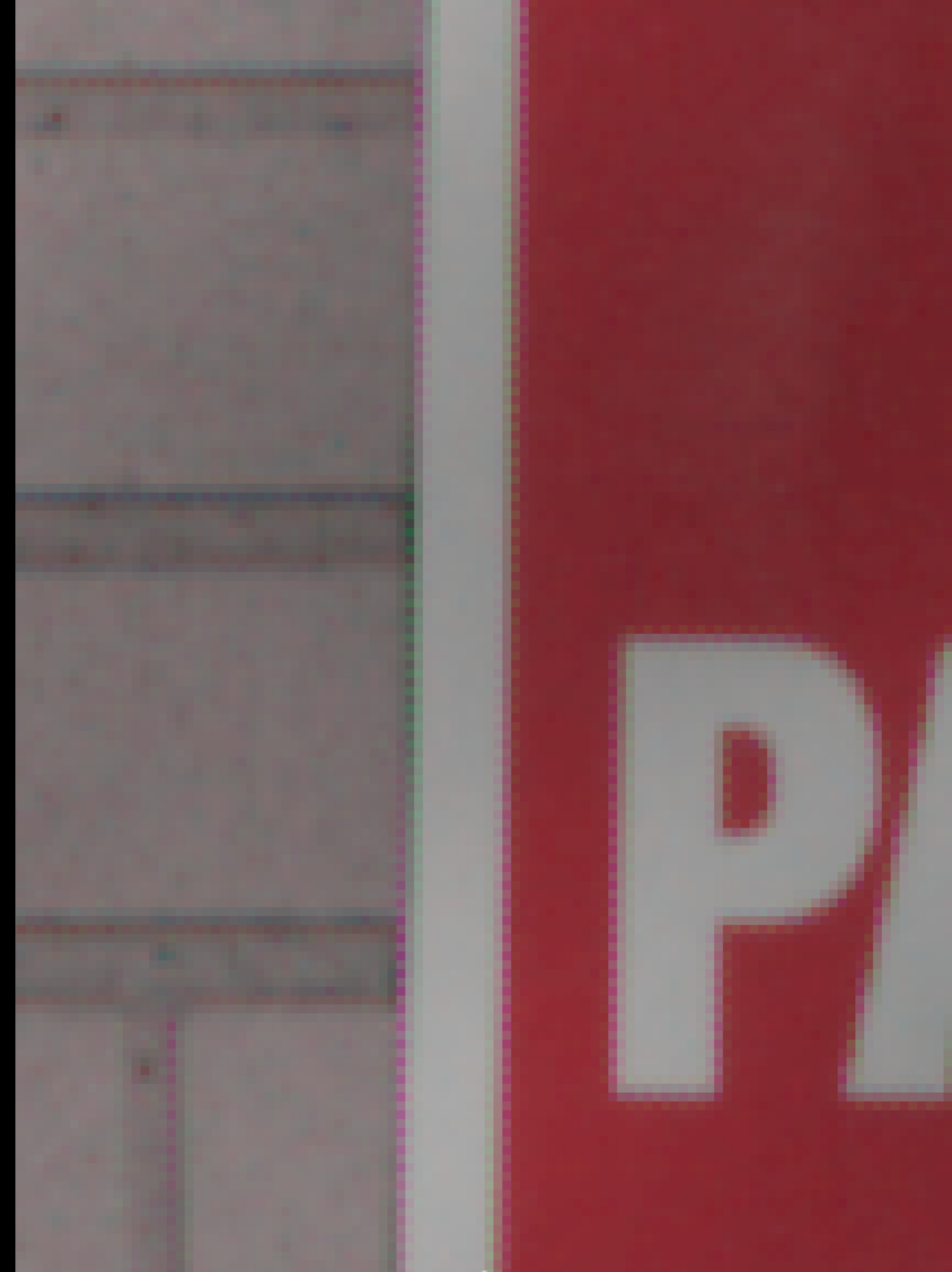
Linear interpolation

Average the 4 or 2 nearest neighbors (linear/tent kernel)

- e.g. $\text{newgreen} = 0.25 * (\text{up} + \text{left} + \text{right} + \text{down})$



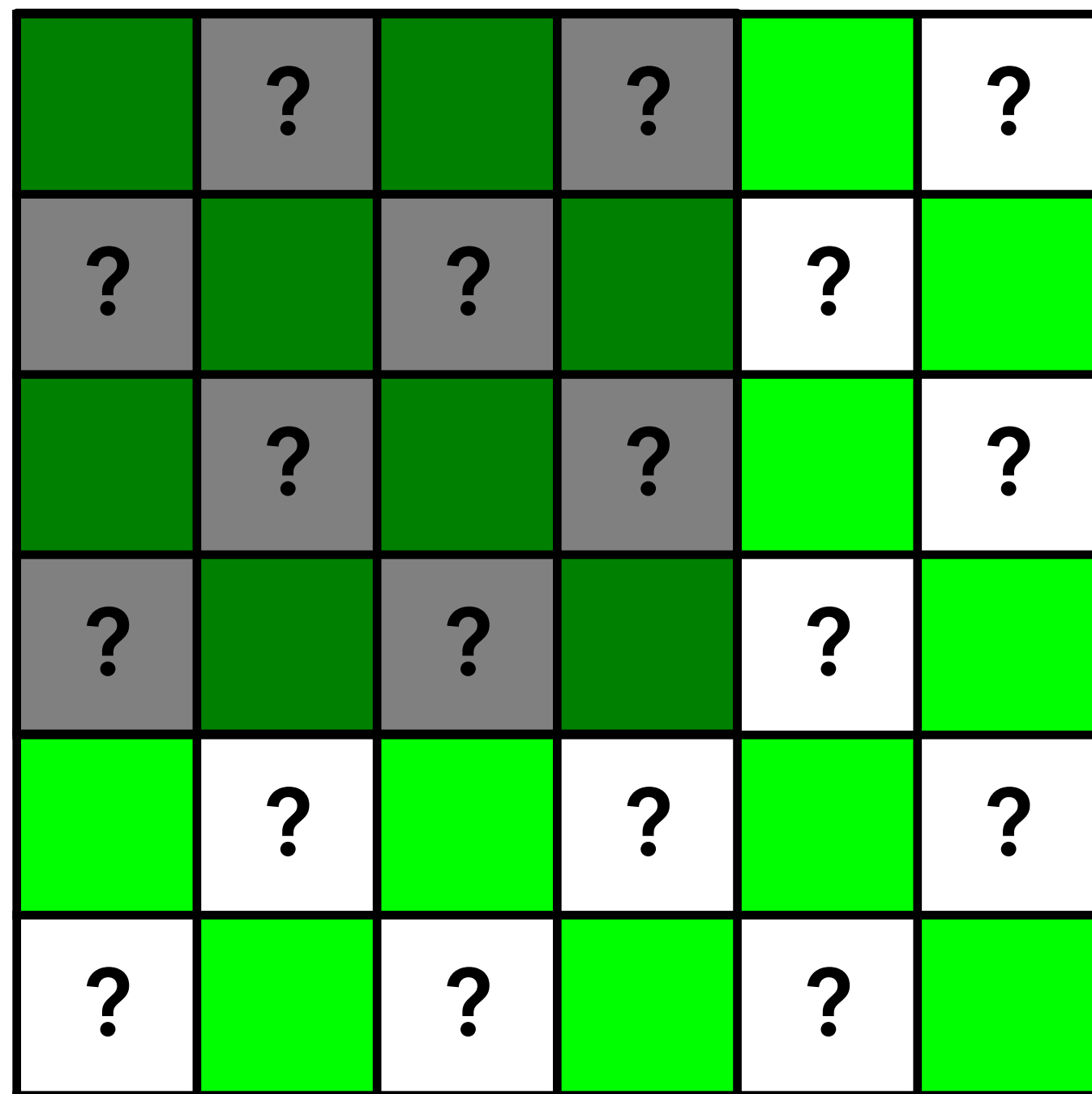
Results - not perfect



The problem

Imagine a black-on-white corner

Let's focus on the green channel for now



The problem

Imagine a black-on-white corner

Let's focus on the green channel for now

	?		?		?
?		?		?	
	?		?		?
?		?		?	
	?		?		?
?		?		?	

0		0		1	
	0		0		1
0		0		1	
	0		0		1
1		1		1	
	1		1		1

The problem

Imagine a black-on-white corner

Let's focus on the green channel for now

	?		?		?
?		?		?	
	?		?		?
?		?		?	
	?		?		?
?		?		?	

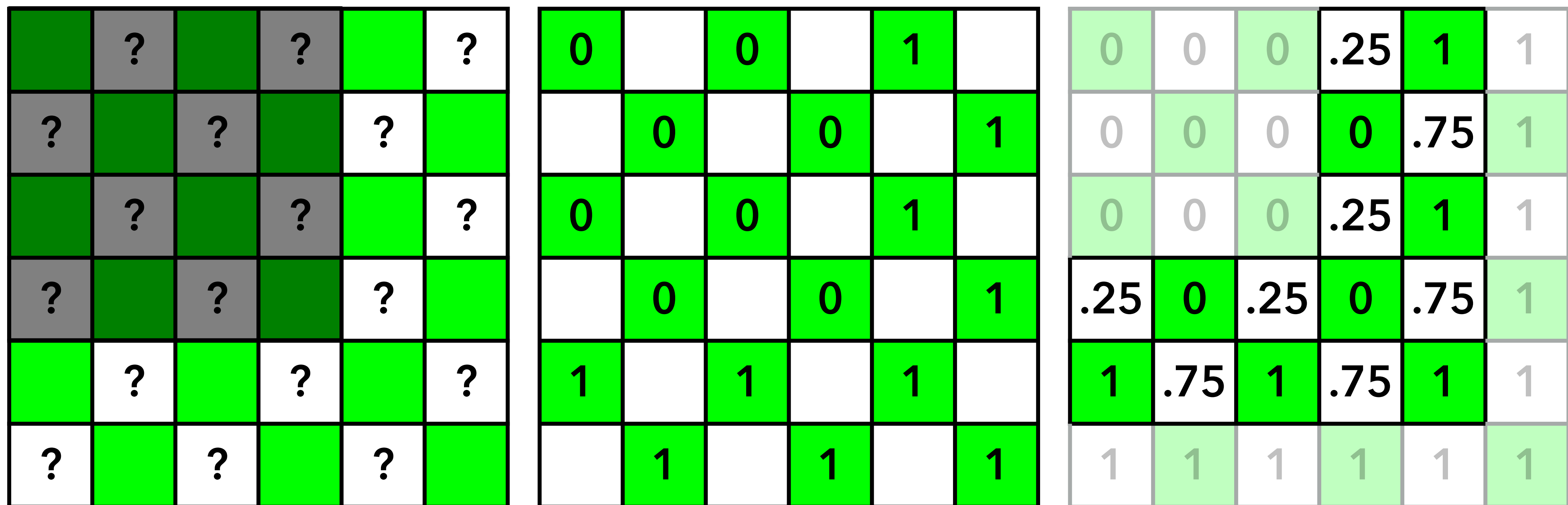
0		0		1	
	0		0		1
0		0		1	
	0		0		1
1		1		1	
	1		1		1

0	0	0	.25	1	1
0	0	0	0	.75	1
0	0	0	.25	1	1
.25	0	.25	0	.75	1
1	.75	1	.75	1	1
1	1	1	1	1	1

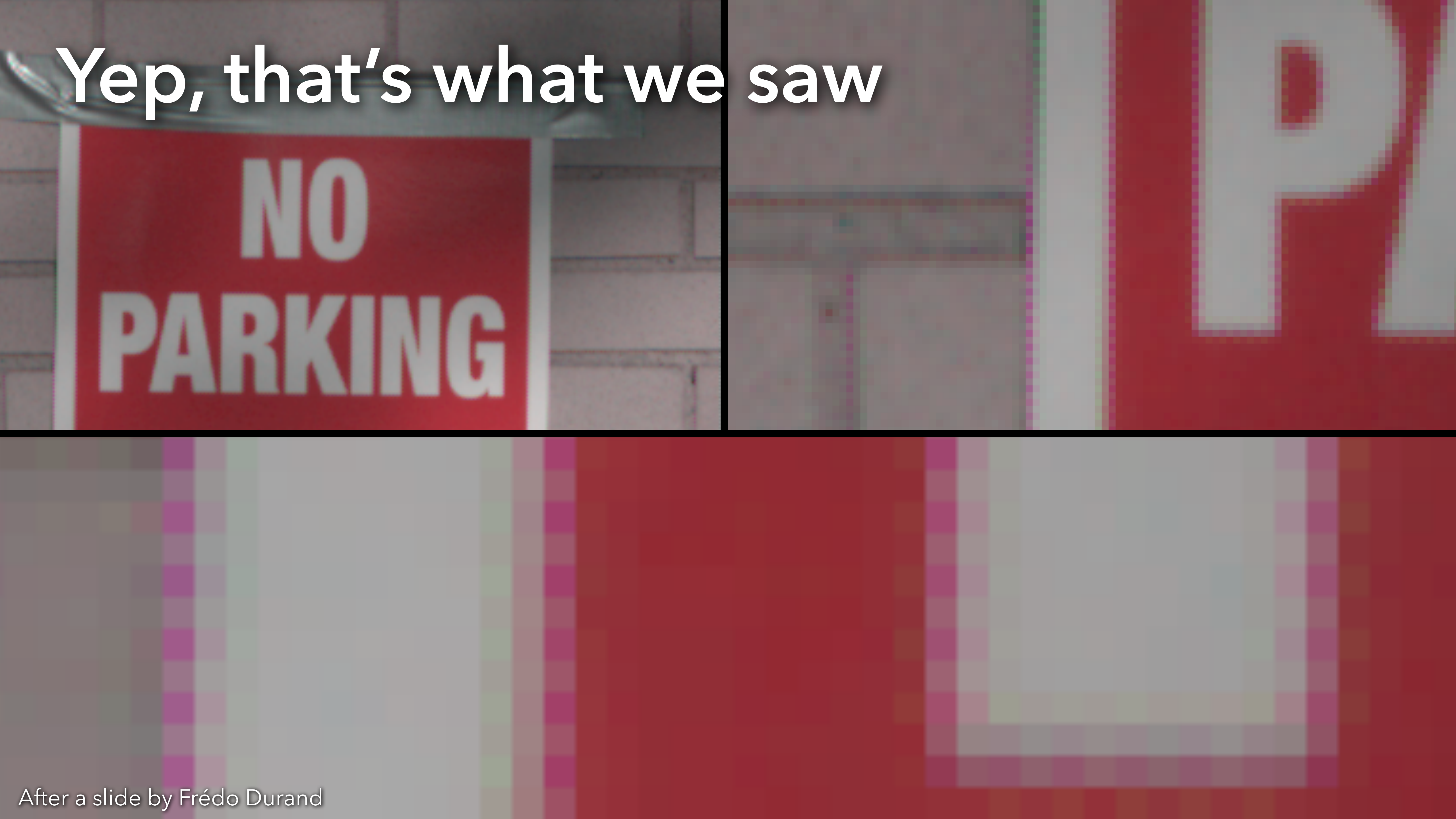
The problem

Imagine a black-on-white corner

Let's focus on the green channel for now



Yep, that's what we saw



Green channel



After a slide by Frédo Durand



Edge-based Demosaicing

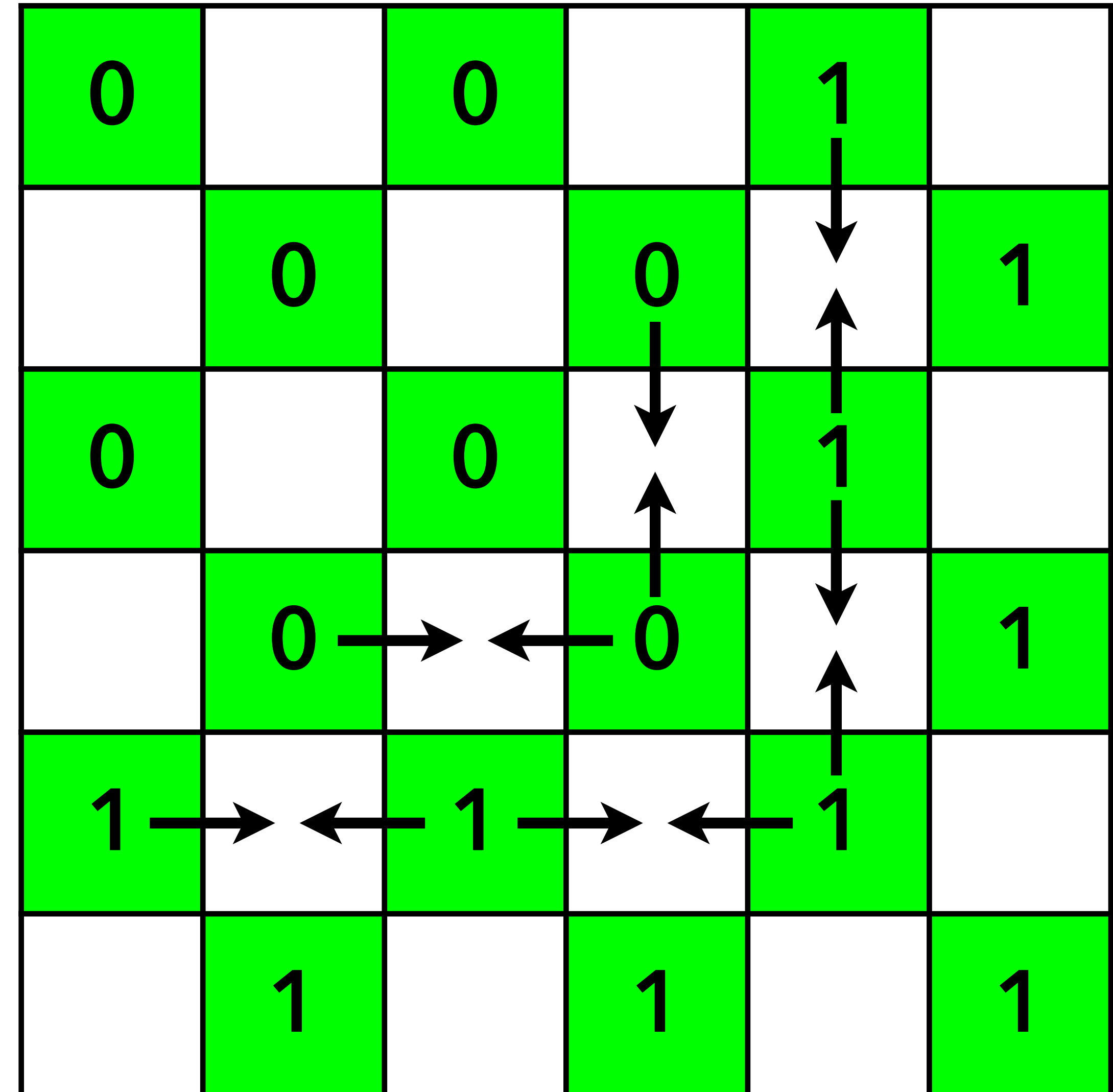
Idea

Take into account structure in image

- Here, 1D edges

Interpolate along preferred direction

- In our case, only use 2 neighbors

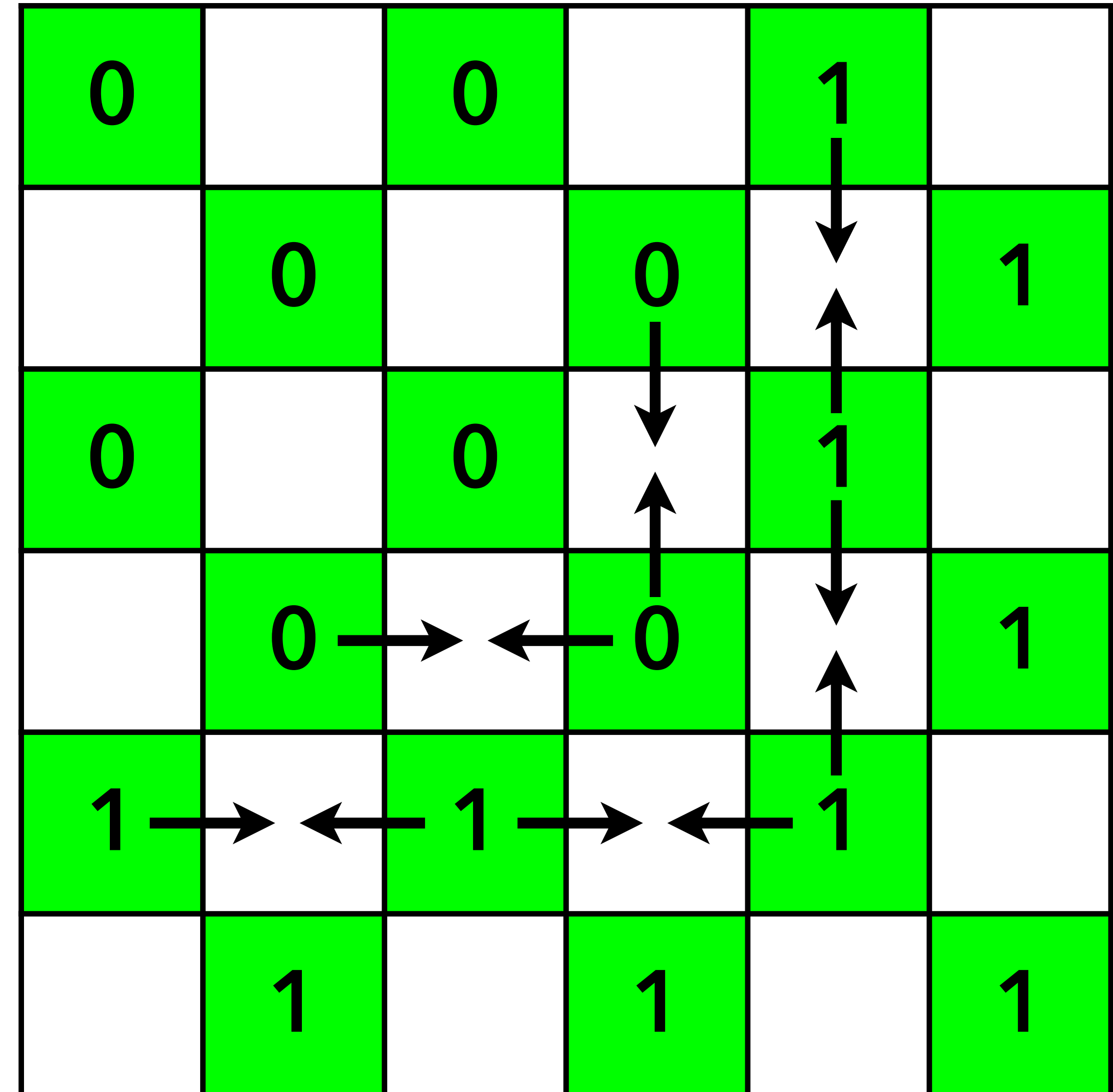


How do we decide?

Look at the similarity of recorded neighbors

- Compare $|\text{up-down}|$ to $|\text{right-left}|$
- Be smart
- See Assignment 3

Called edge-based demosaicing



Green channel – naïve



Green channel – edge-based





Challenge with
other channels

Problem

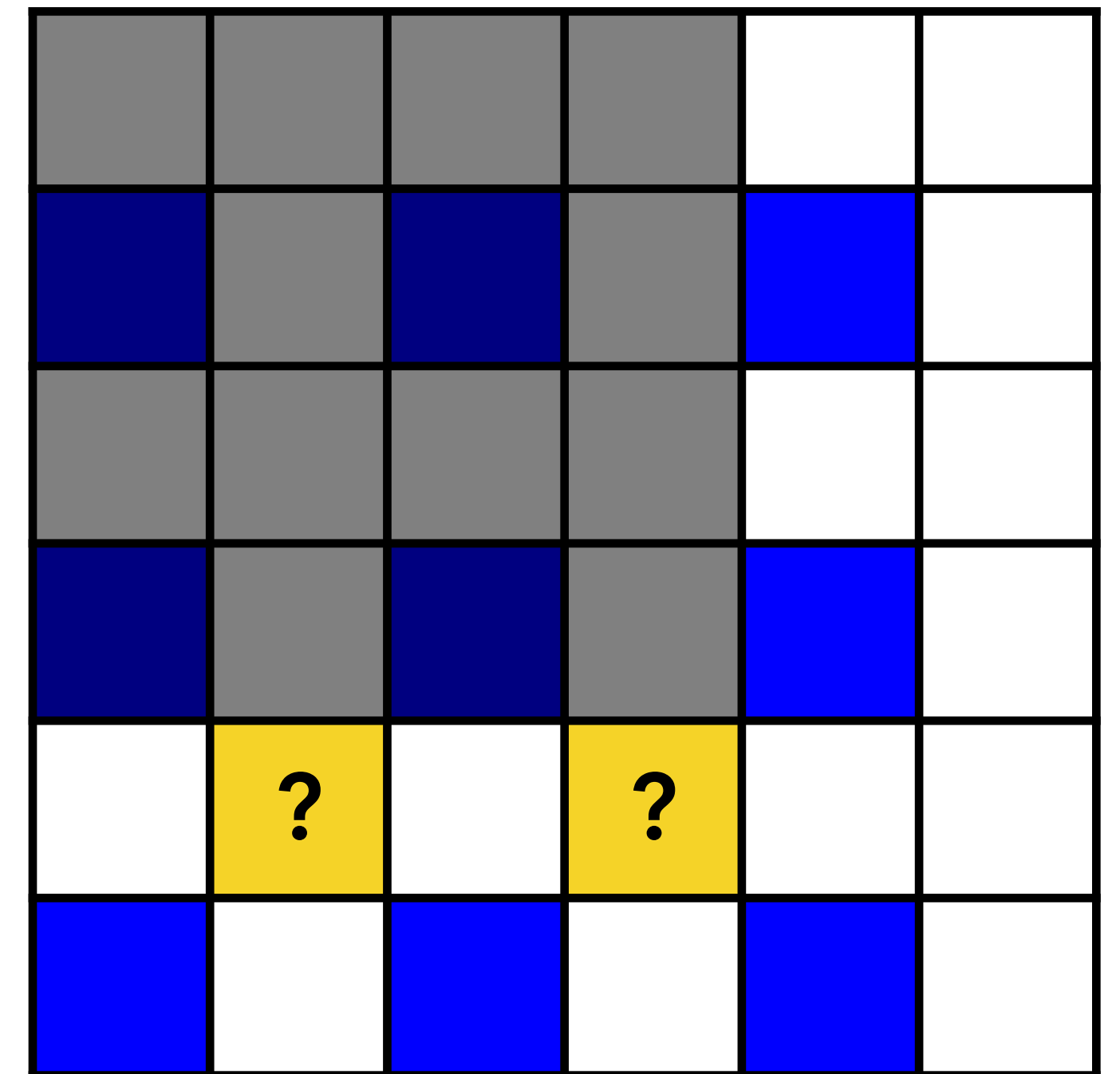
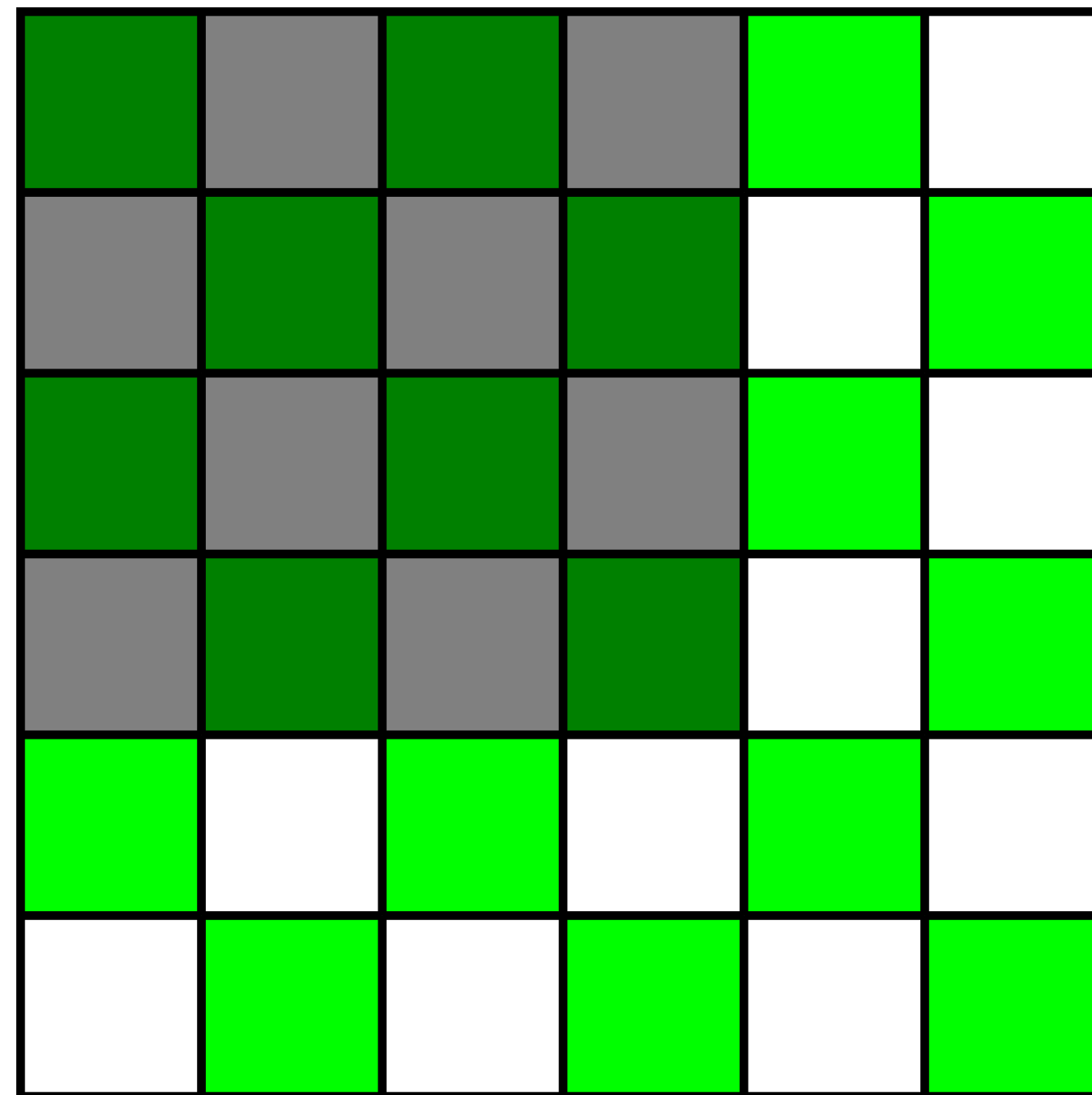
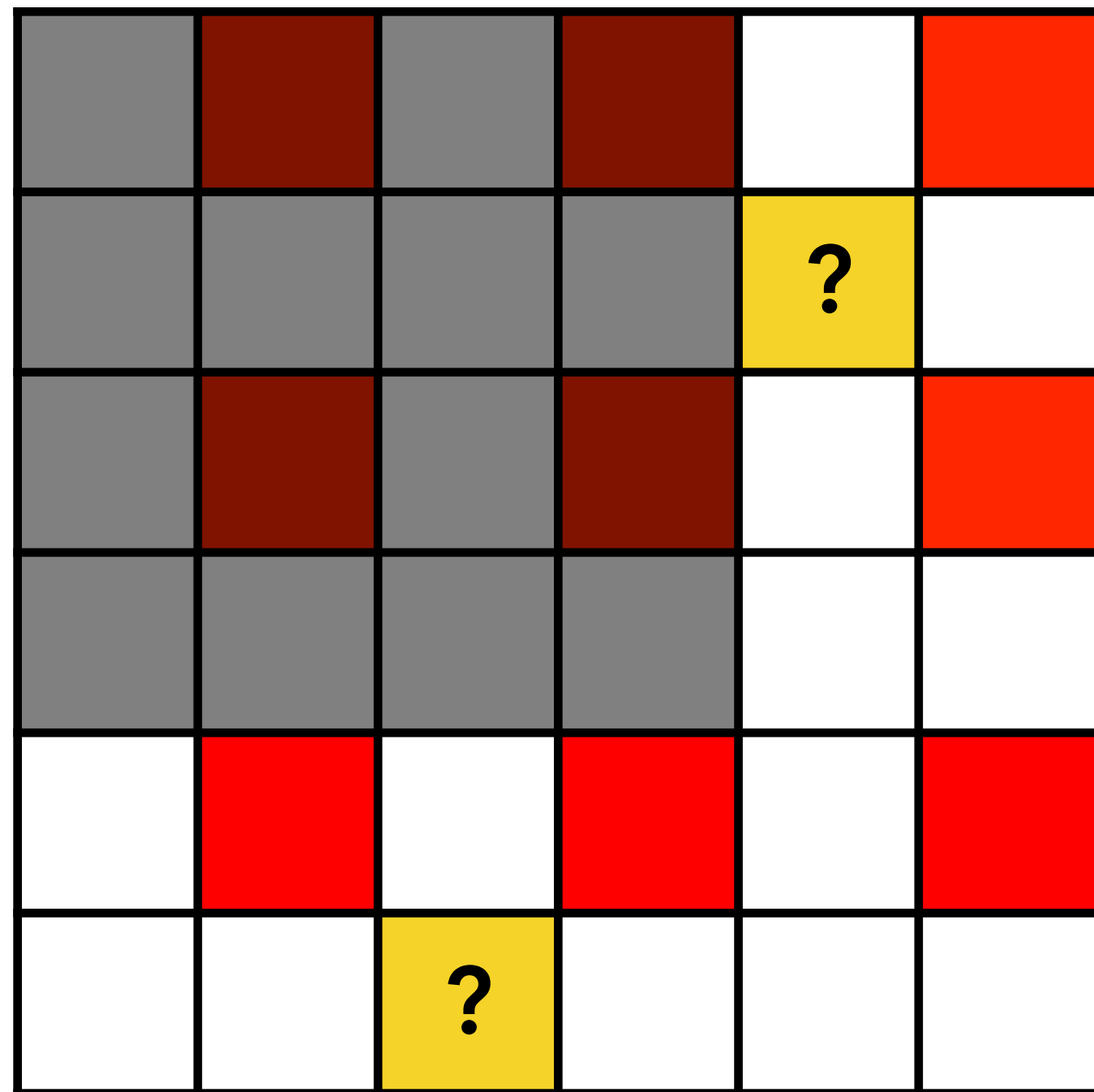
What do we do with red and blue?

We could apply the edge-based principle

- but we're missing more information
- but color transitions might be shifted

Example (black-on-white corner)

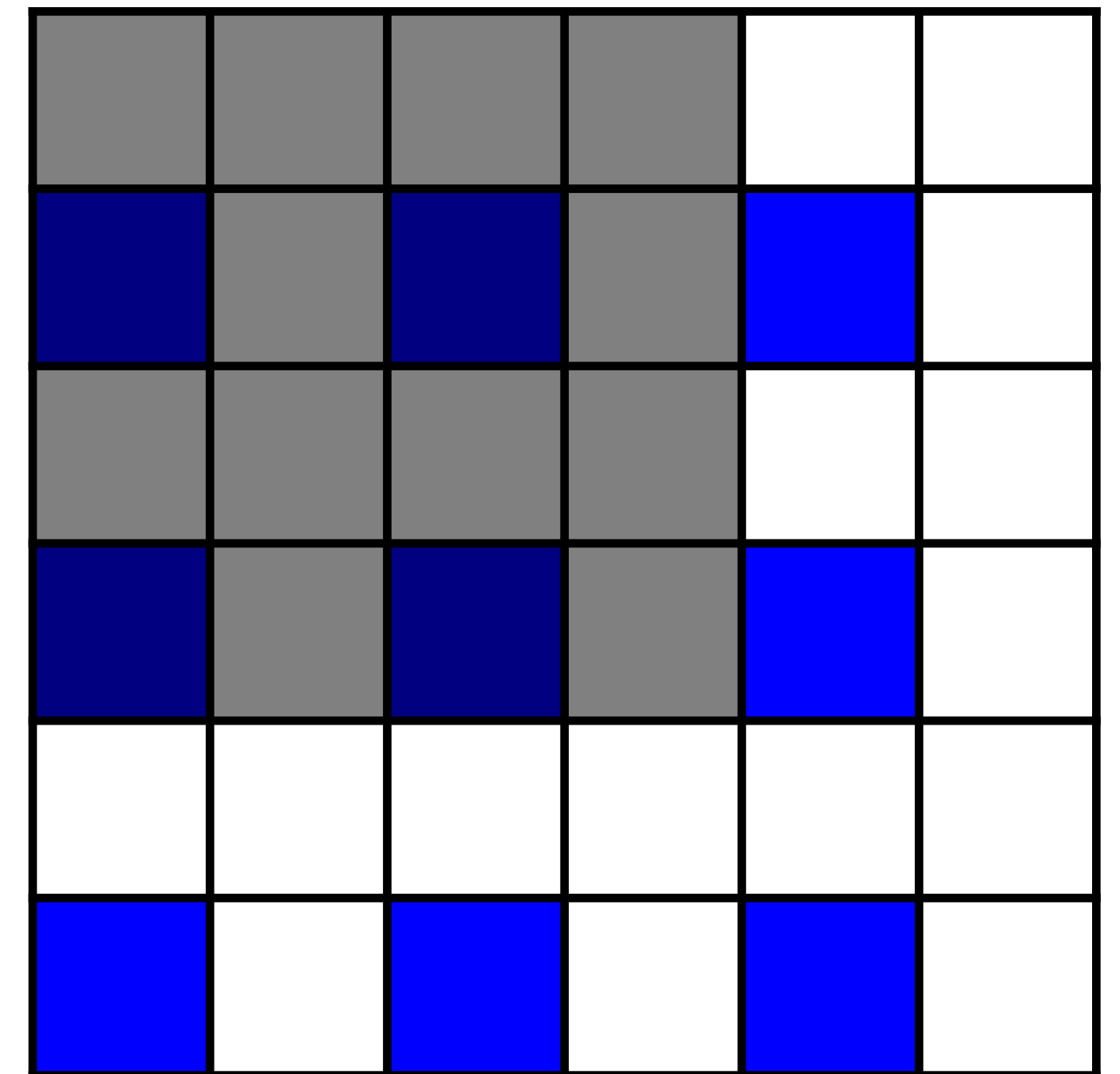
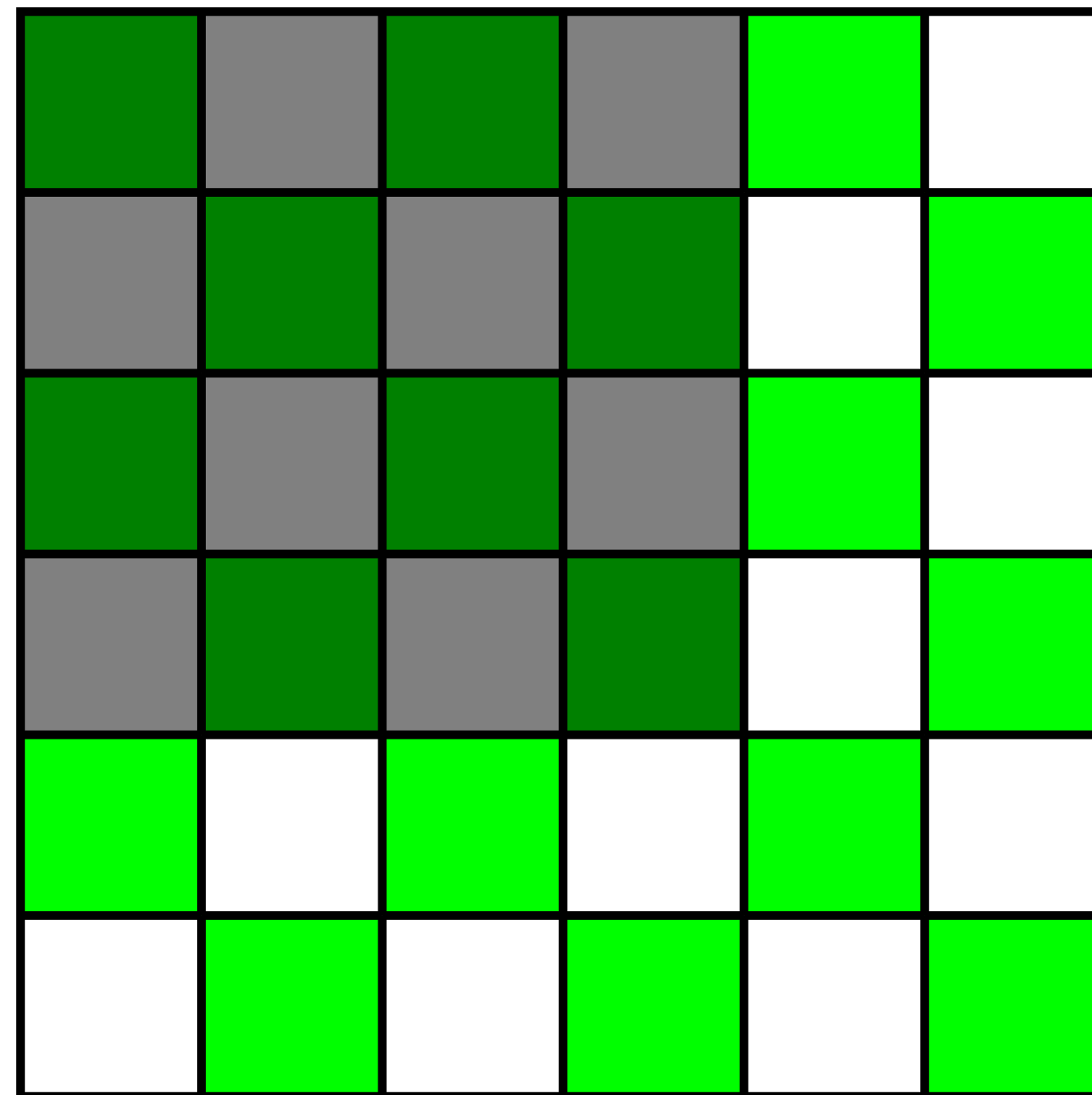
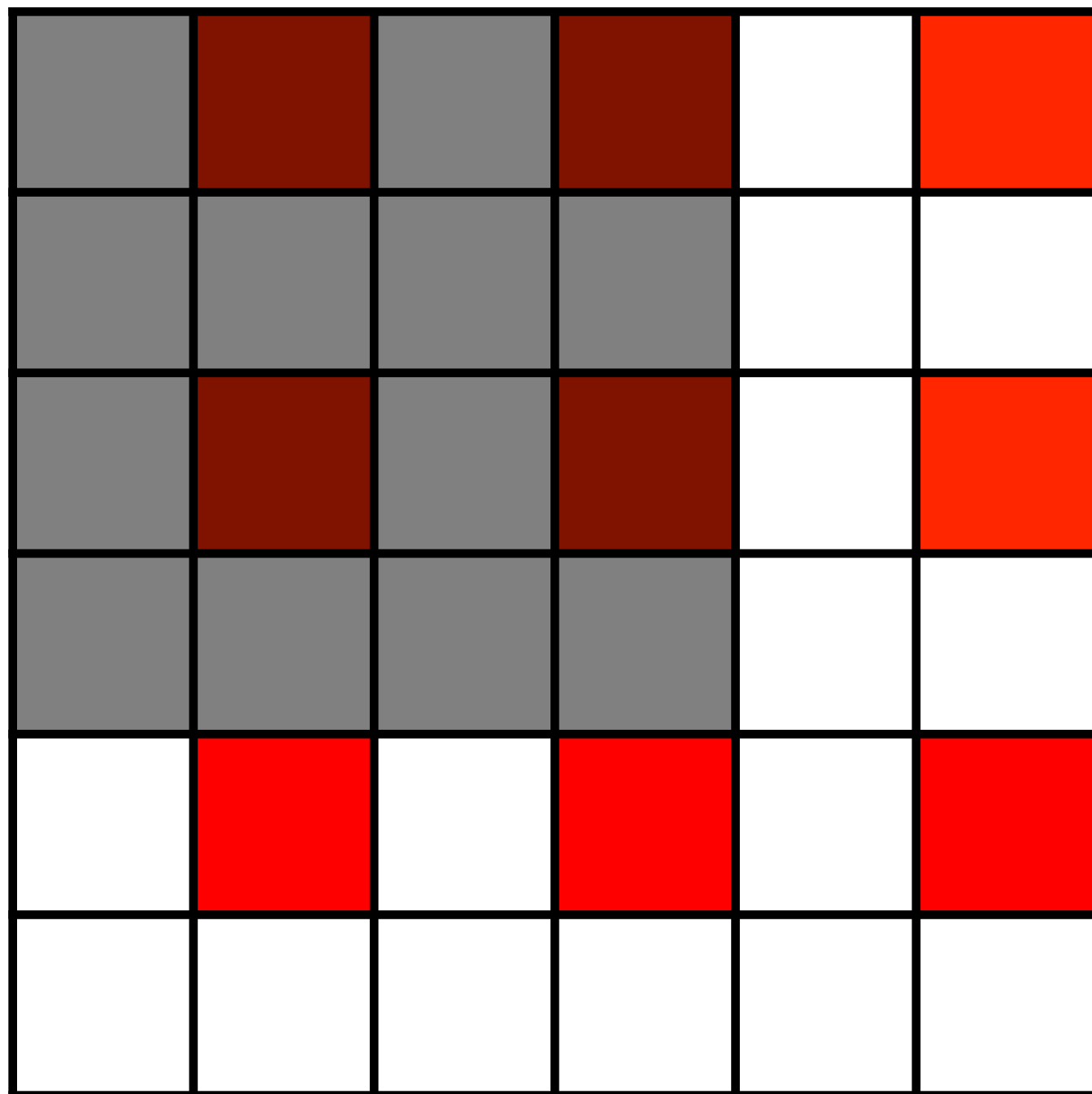
Notion of edges unclear for pixels in empty rows/columns



Example (black-on-white corner)

Even if we could do a decent job for each channel, the channels don't line up

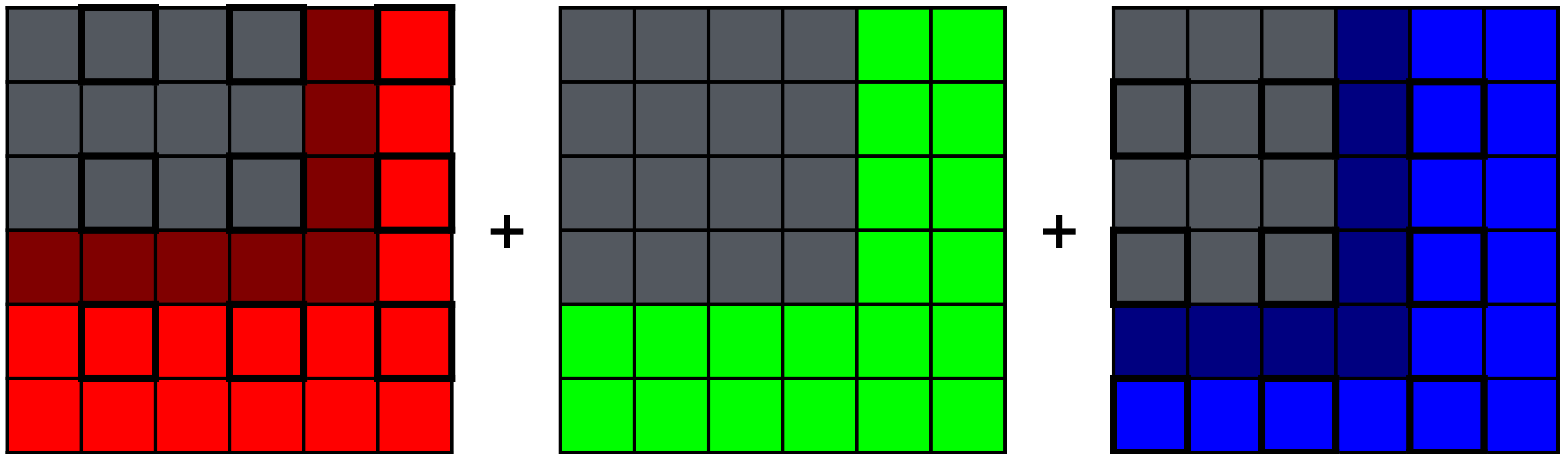
- because they are not recorded at the same location



Example (black-on-white corner)

Even if we could do a decent job for each channel, the channels don't line up

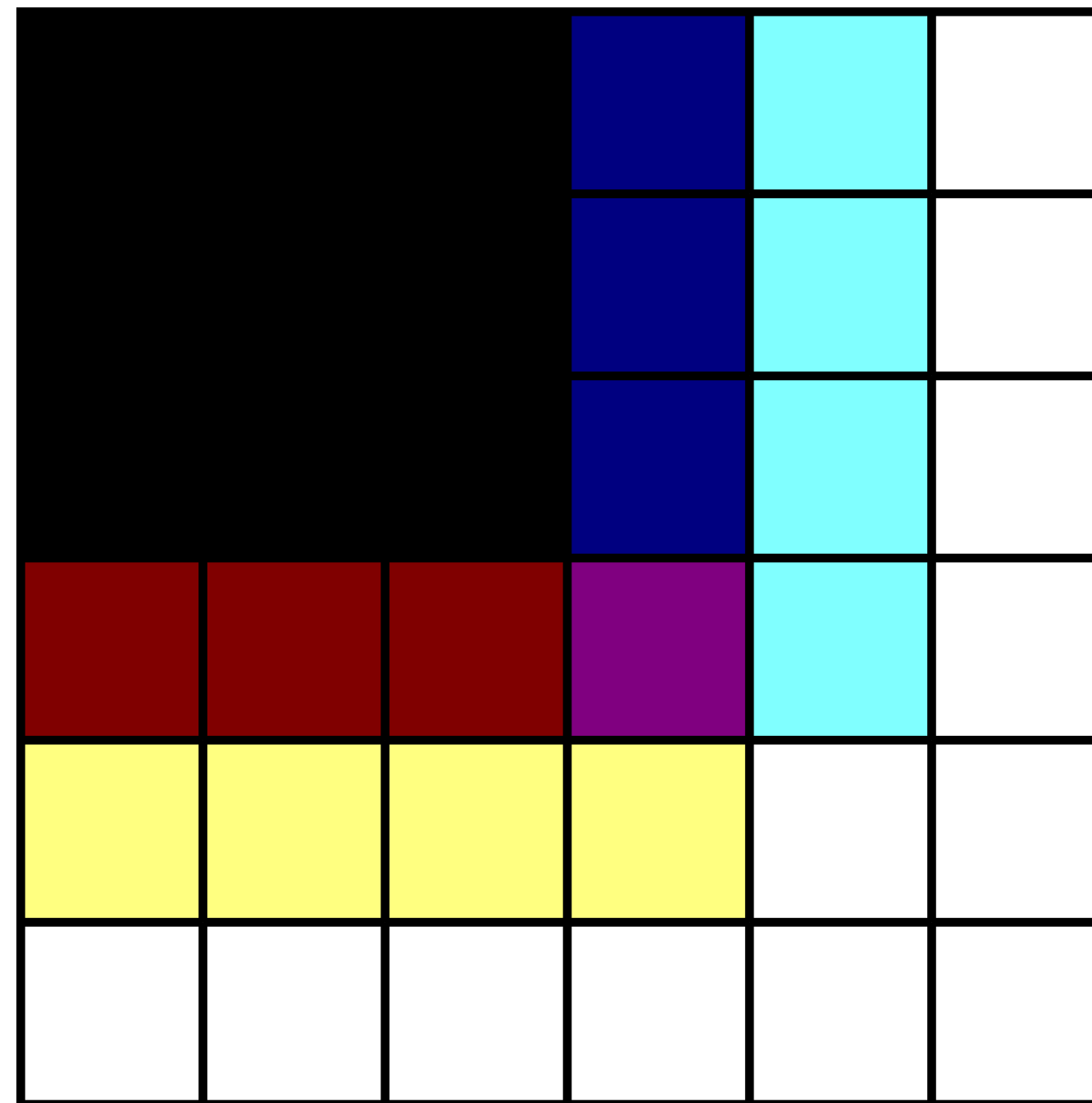
- because they are not recorded at the same location



Example (black-on-white corner)

Even if we could do a decent job for each channel, the channels don't line up

- because they are not recorded at the same location



Bad color fringes!

Recall color artifacts



After a slide by Frédo Durand



Green-based Demosaicing

Green-based demosaicing

Green is a better color channel

- Twice as many pixels
- Often better SNR
- We know how to do edge-based green interpolation

Do the best job you can and get high resolution from green

Then use green to guide red & blue interpolation

Interpolate difference to green

Interpolate green

- using e.g. edge-based

For recorded red pixels

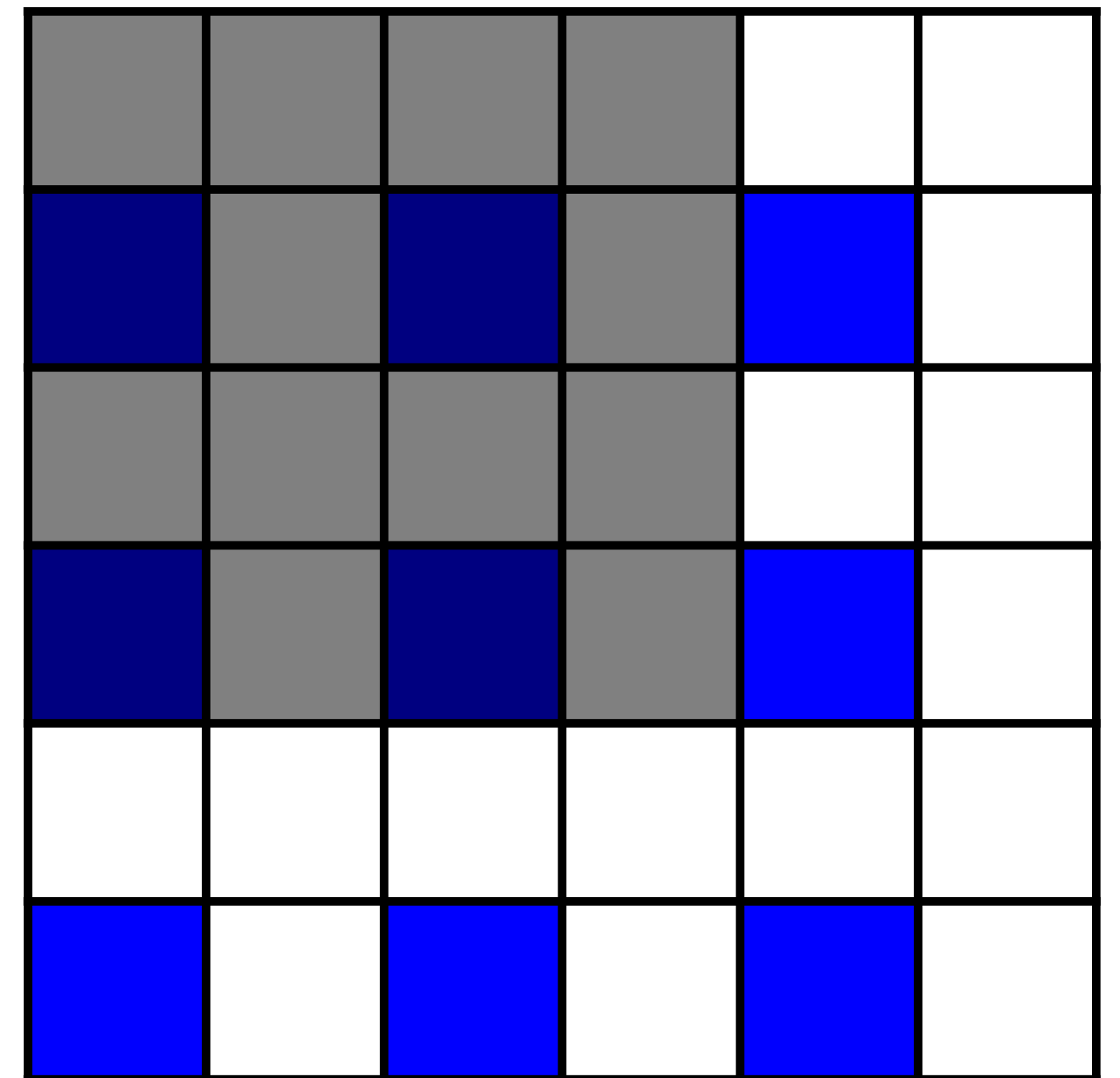
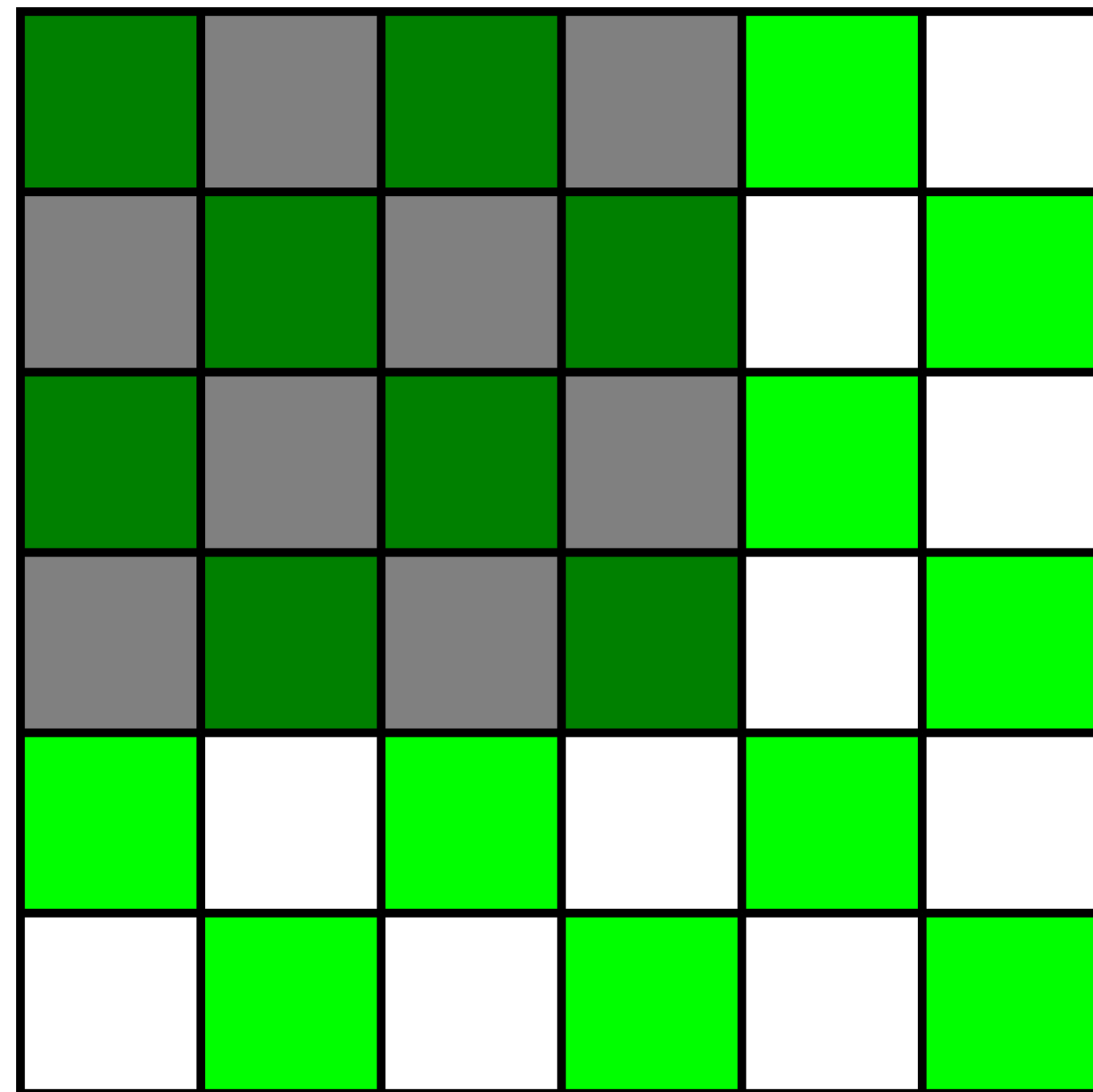
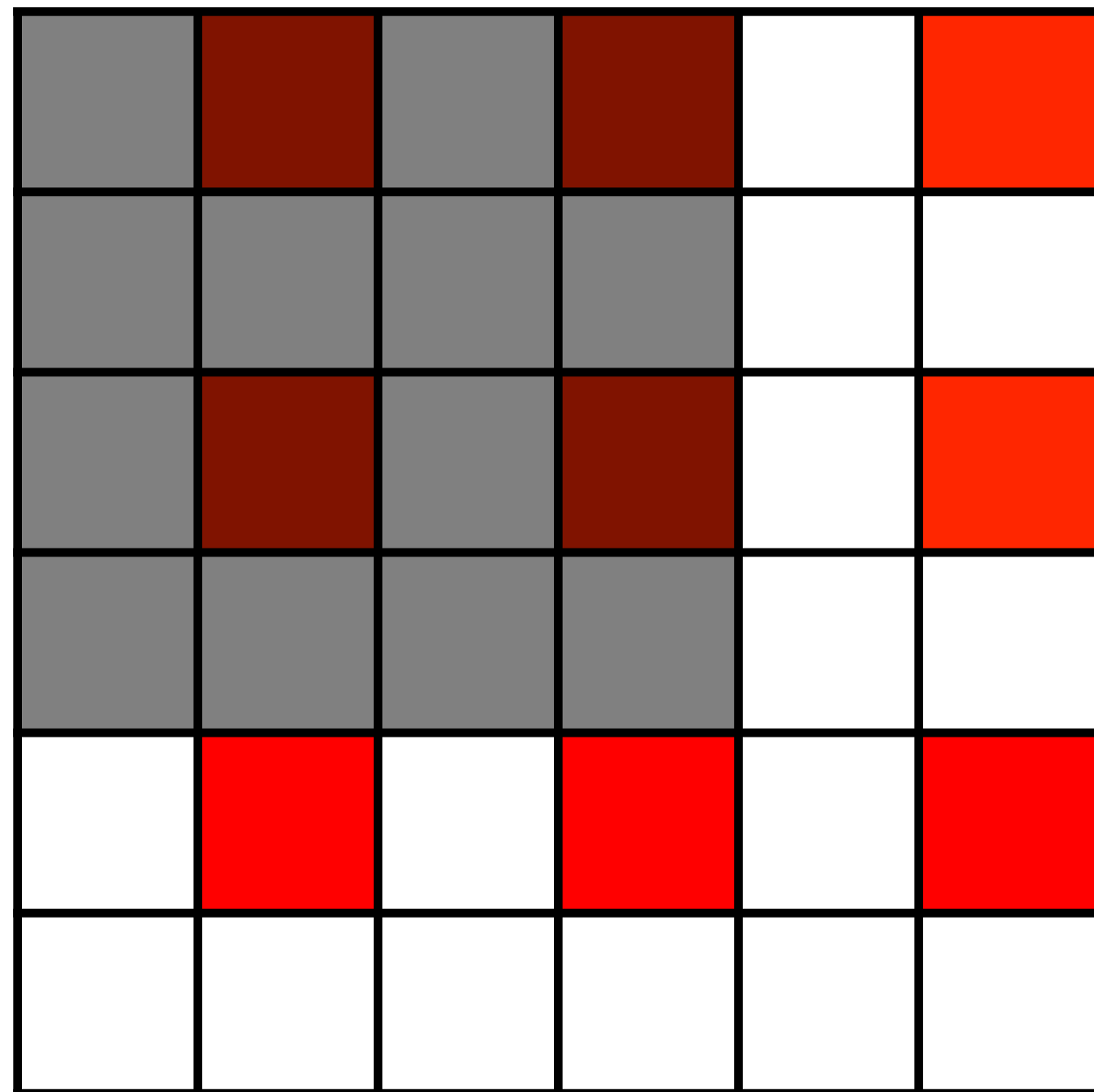
- compute $R-G$

At empty pixels

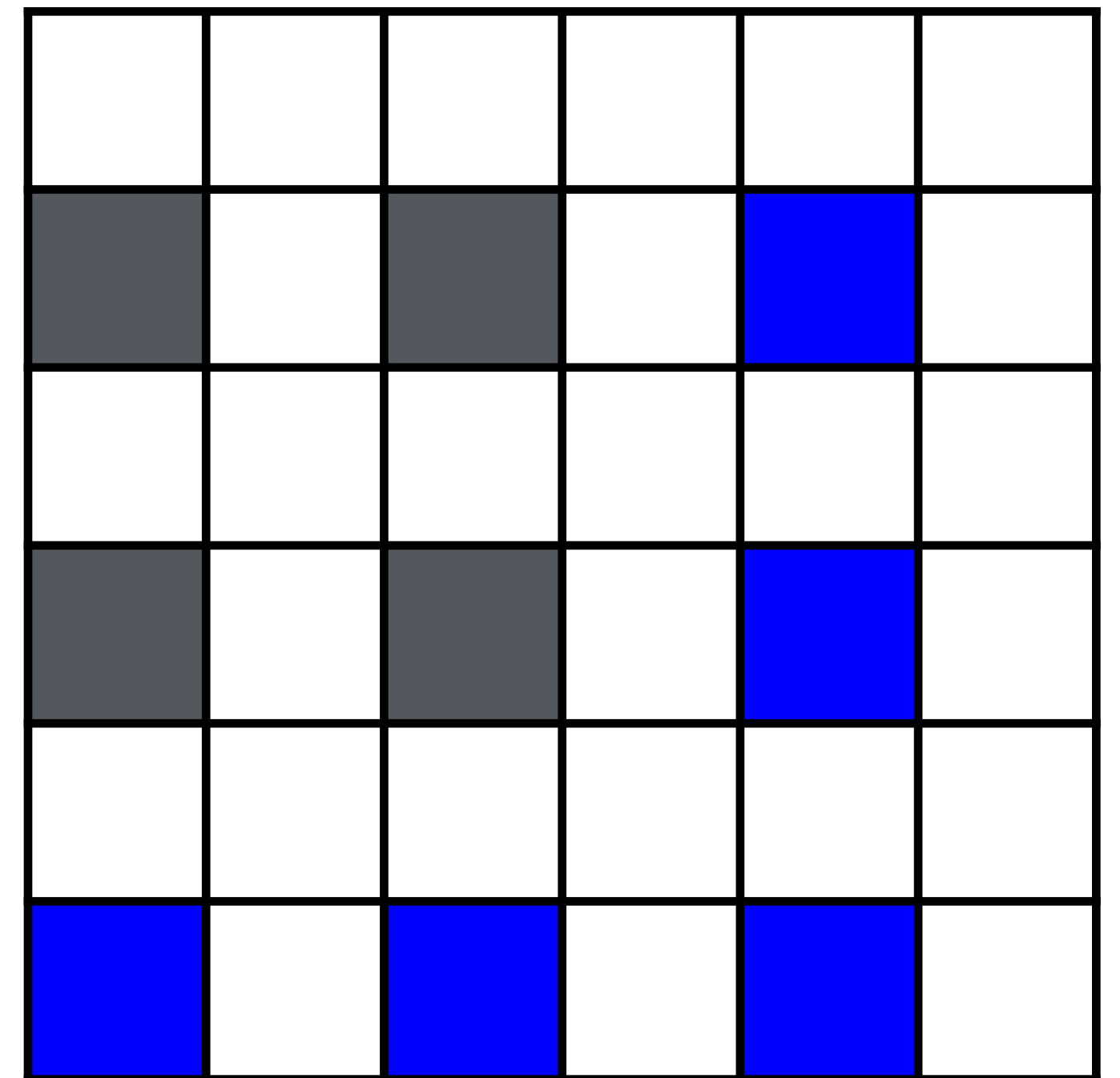
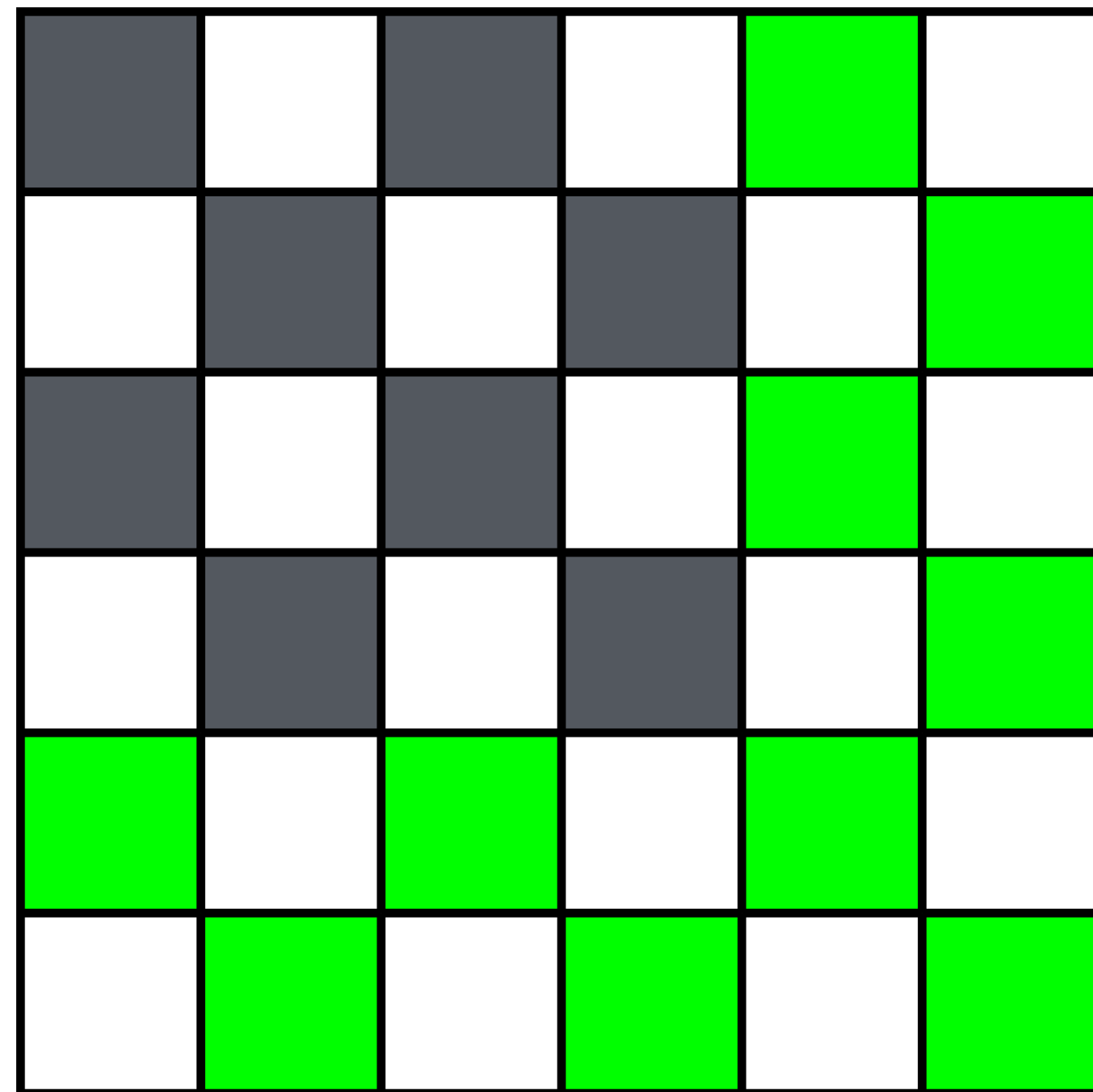
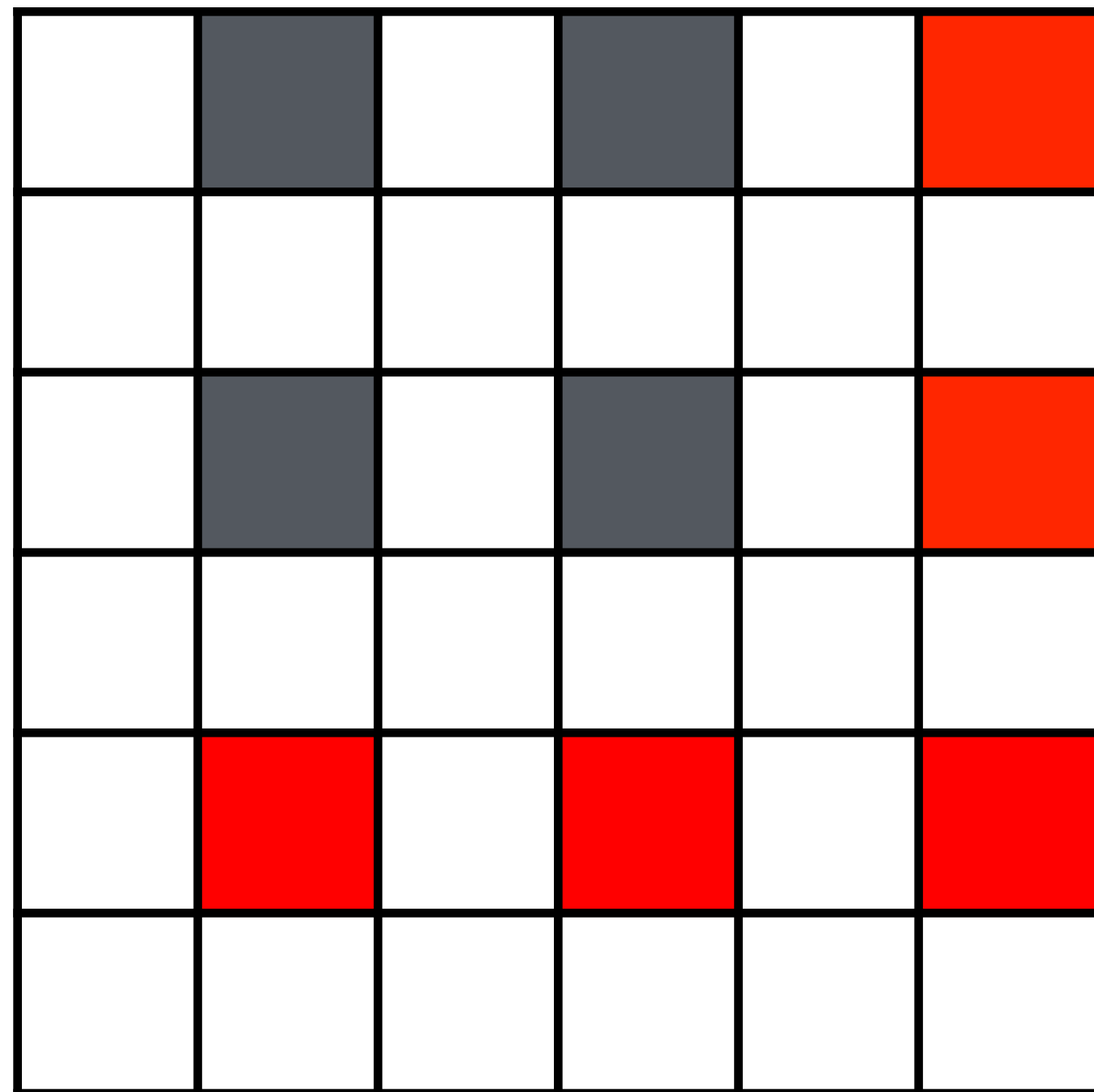
- Interpolate $R-G$ naively
- Add G

Same for blue

Black-on-white corner

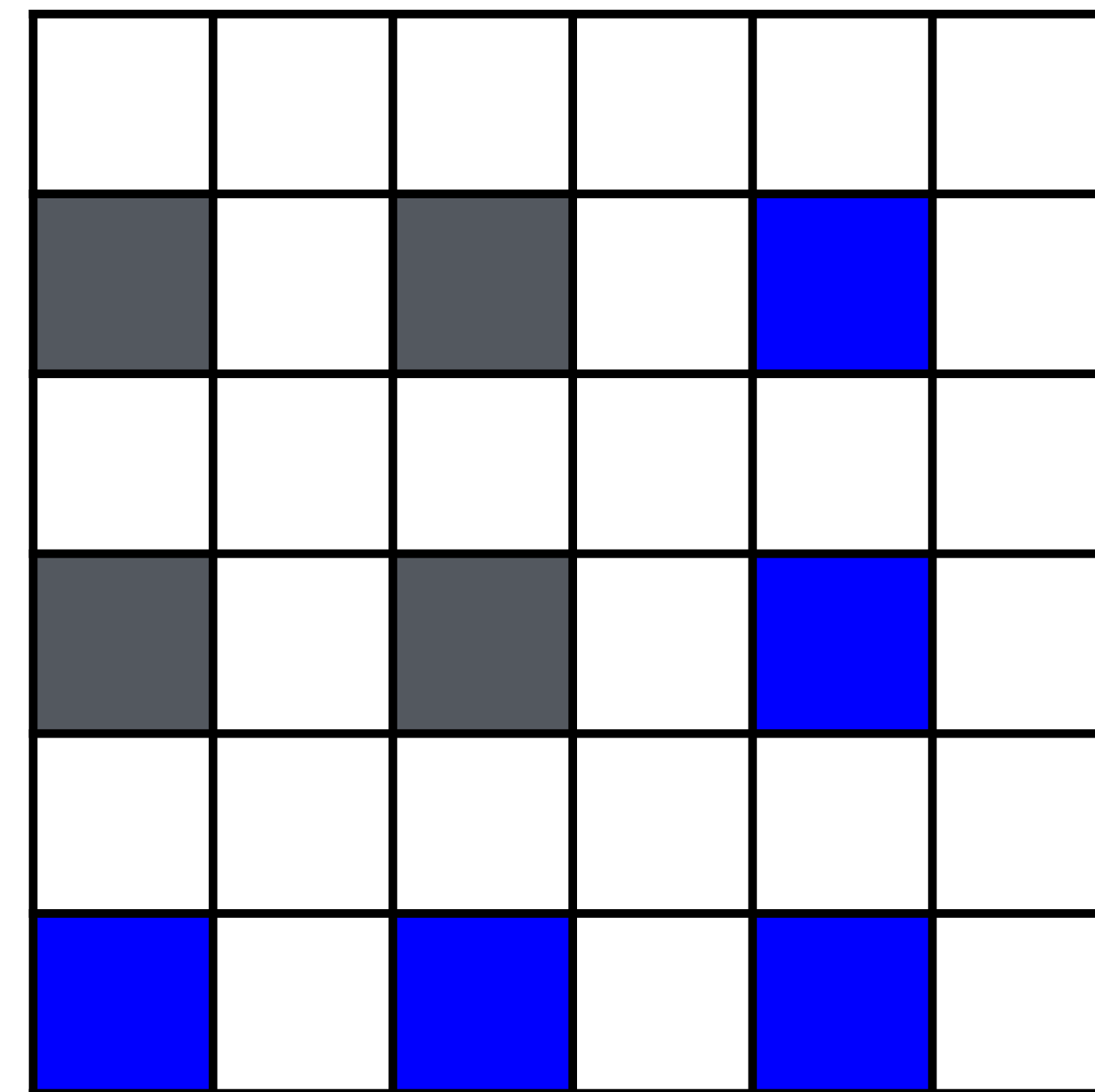
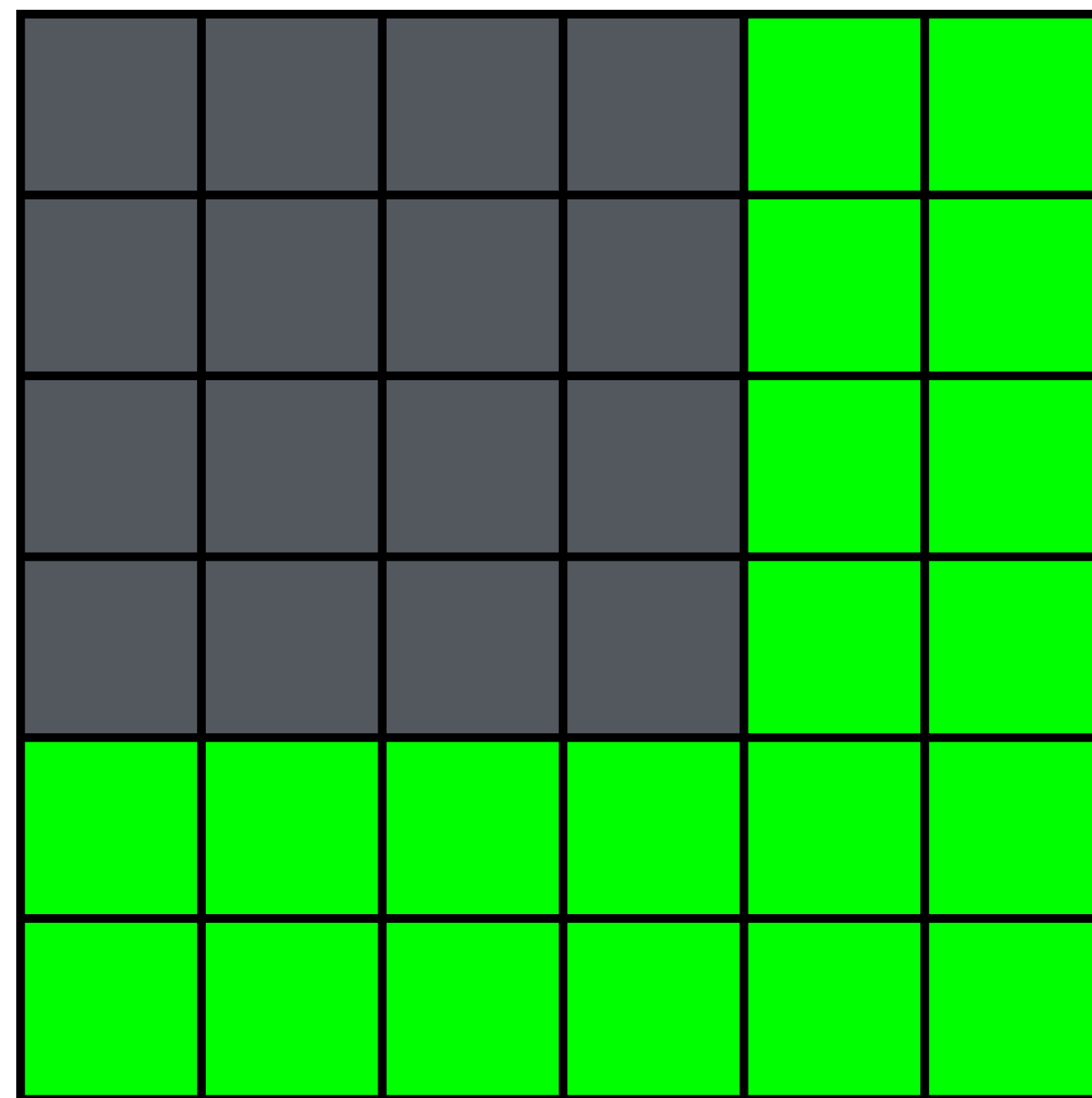
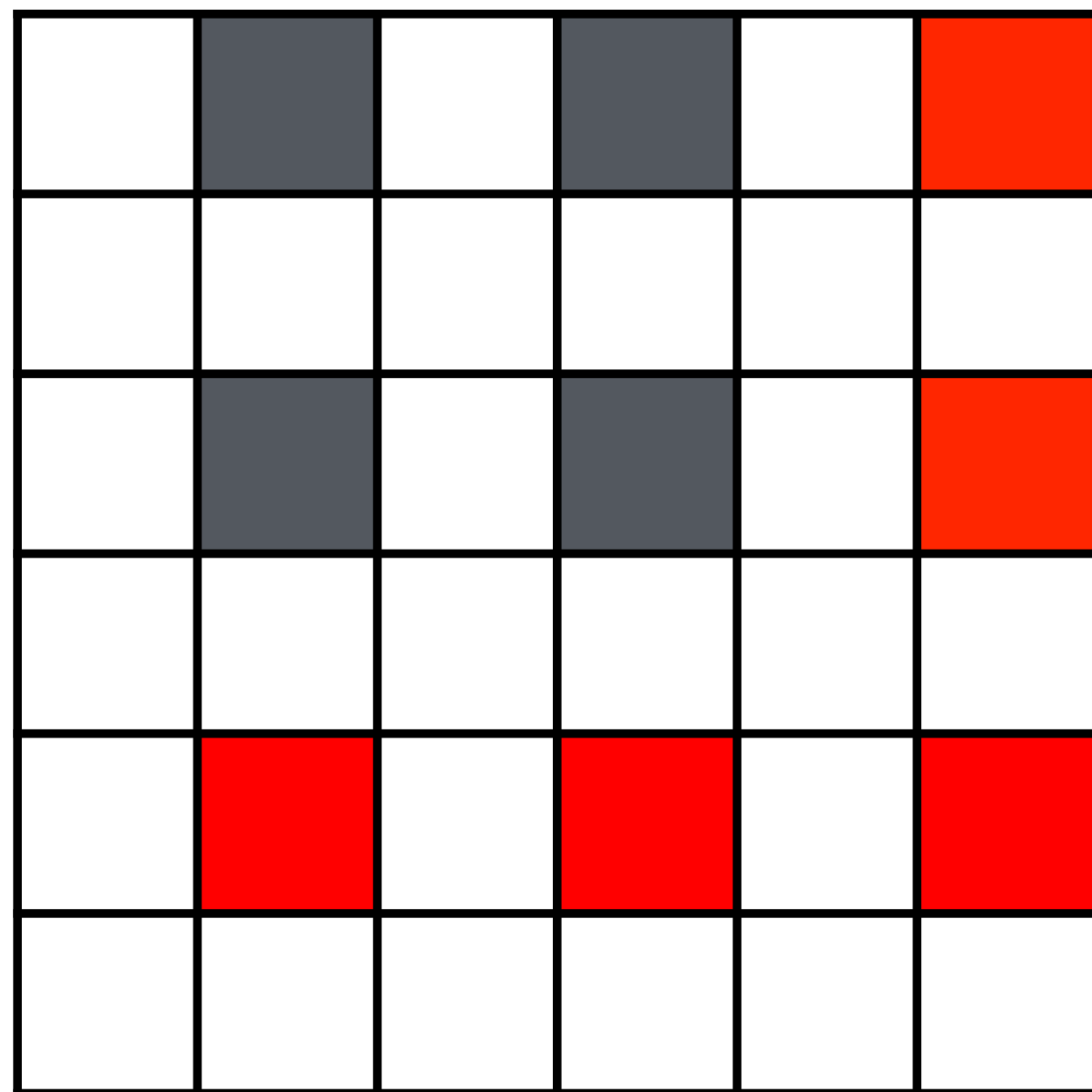


Measurements



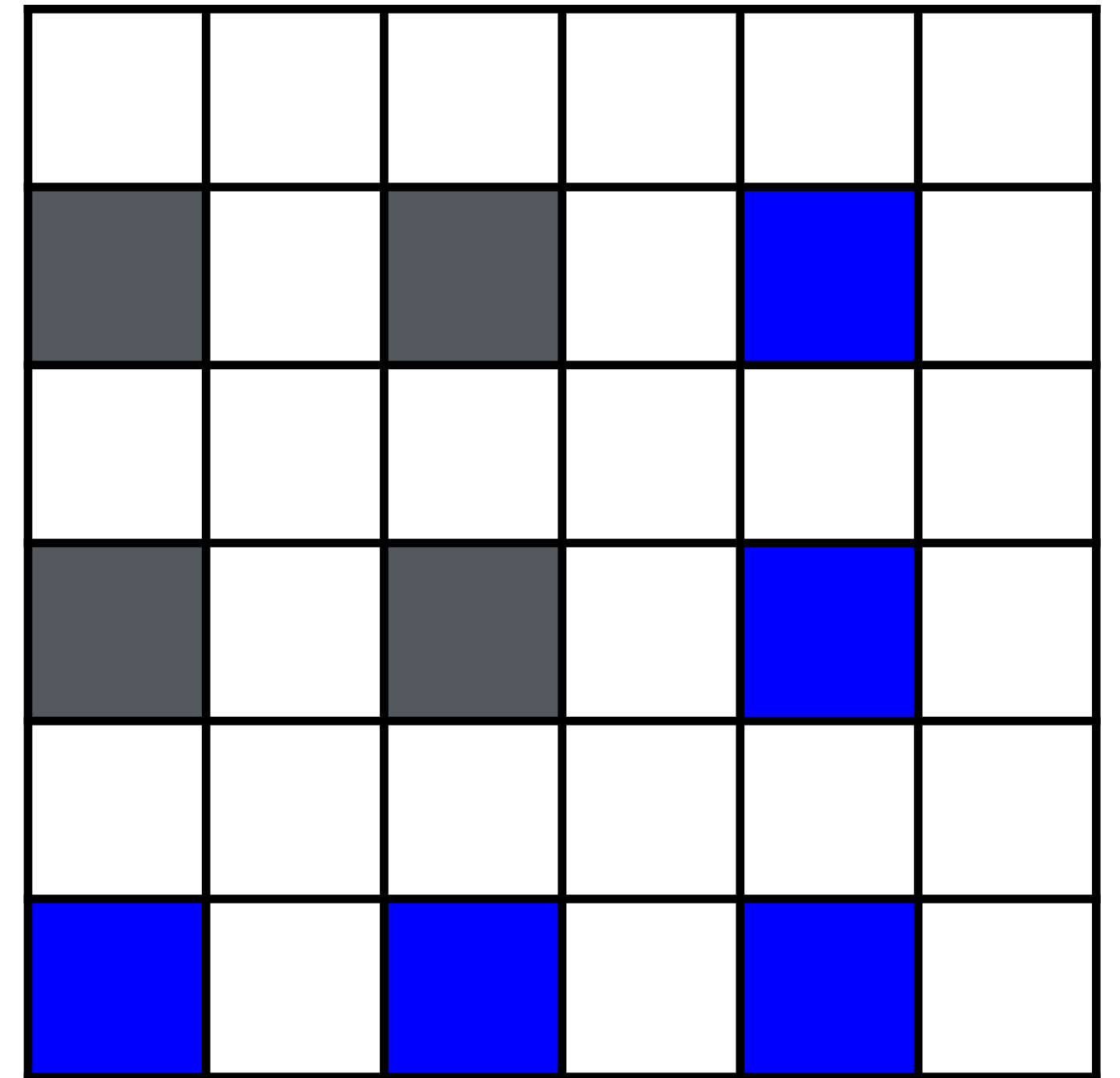
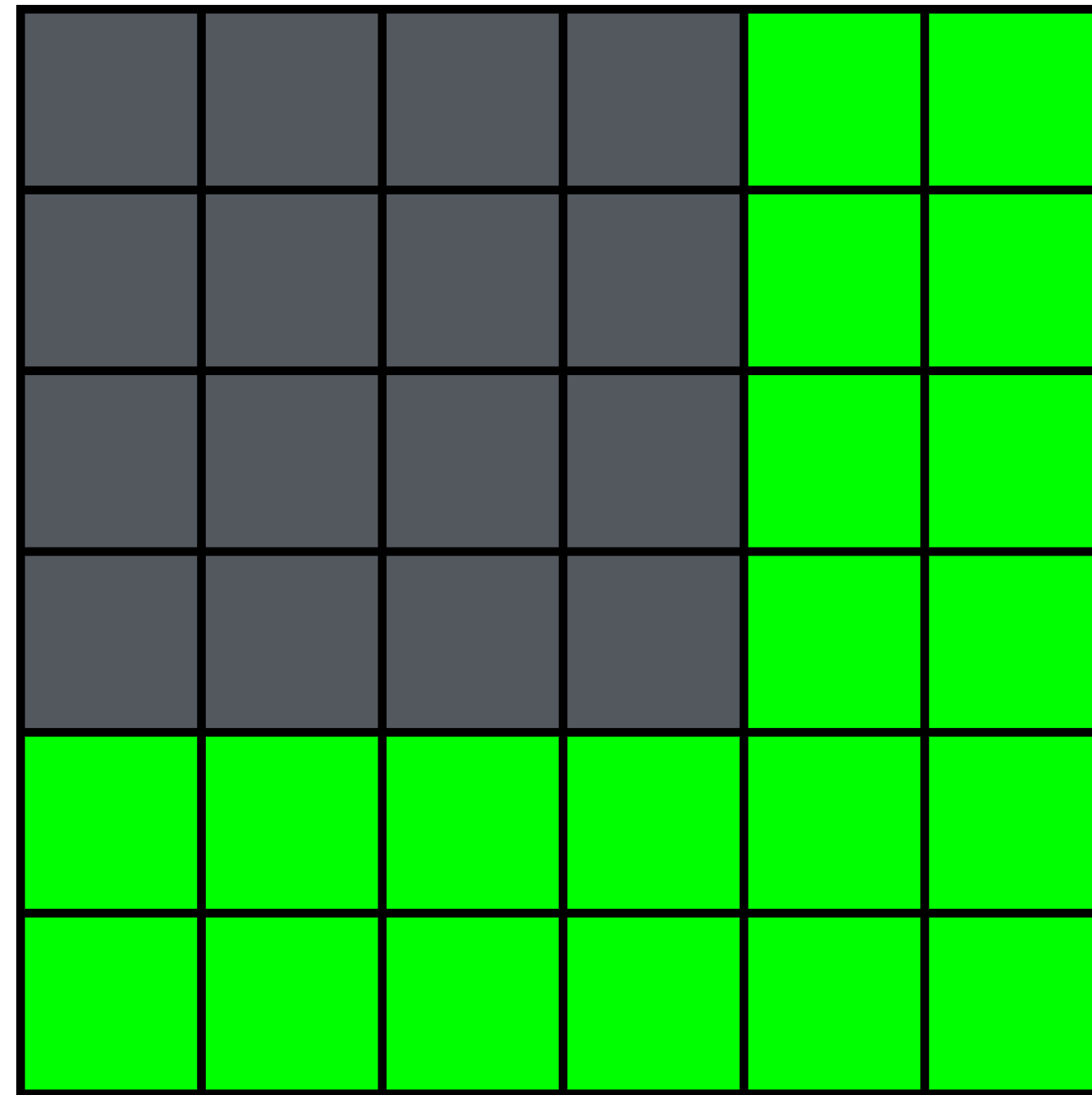
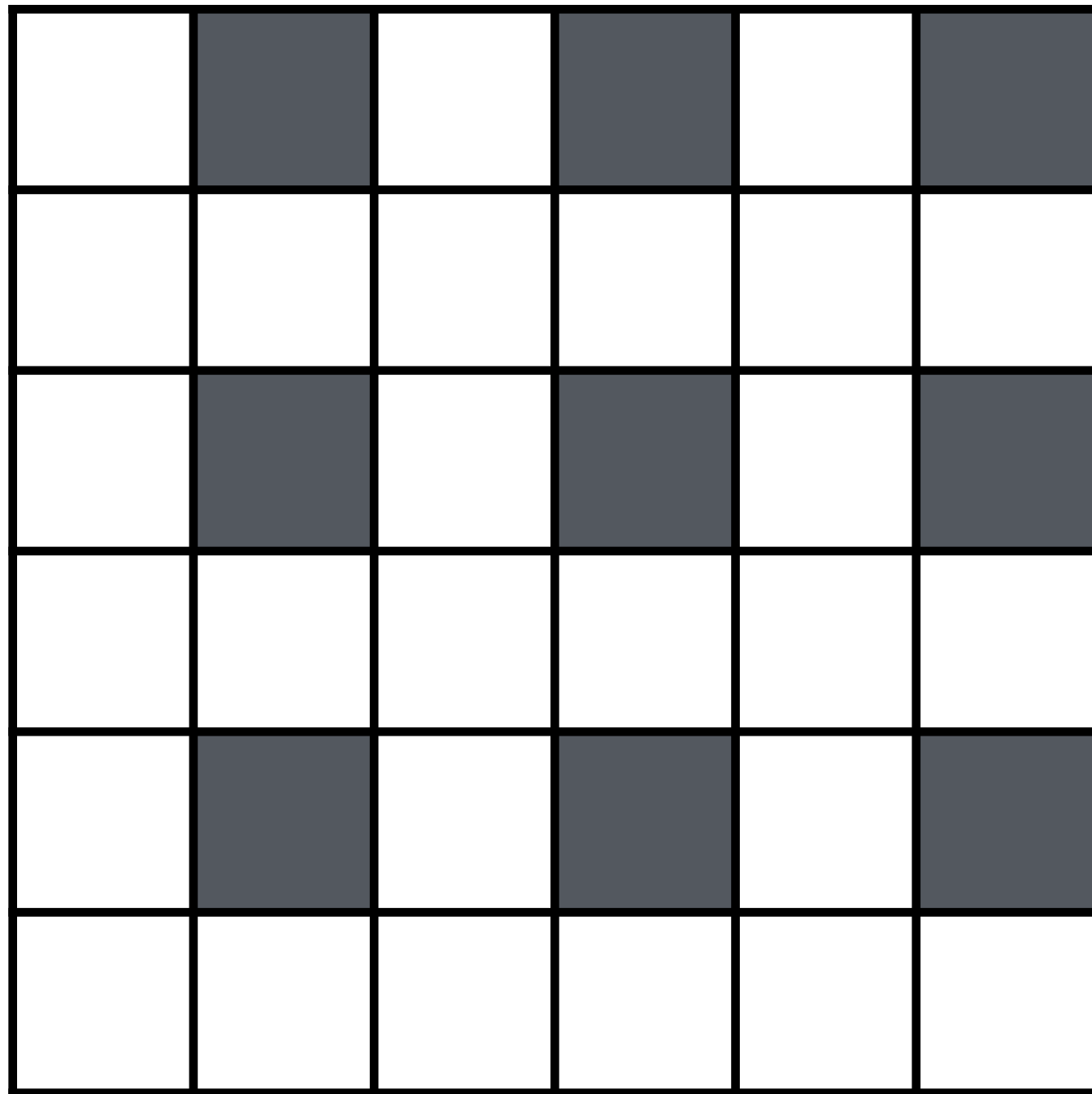


Edge-based green



Red-Green difference

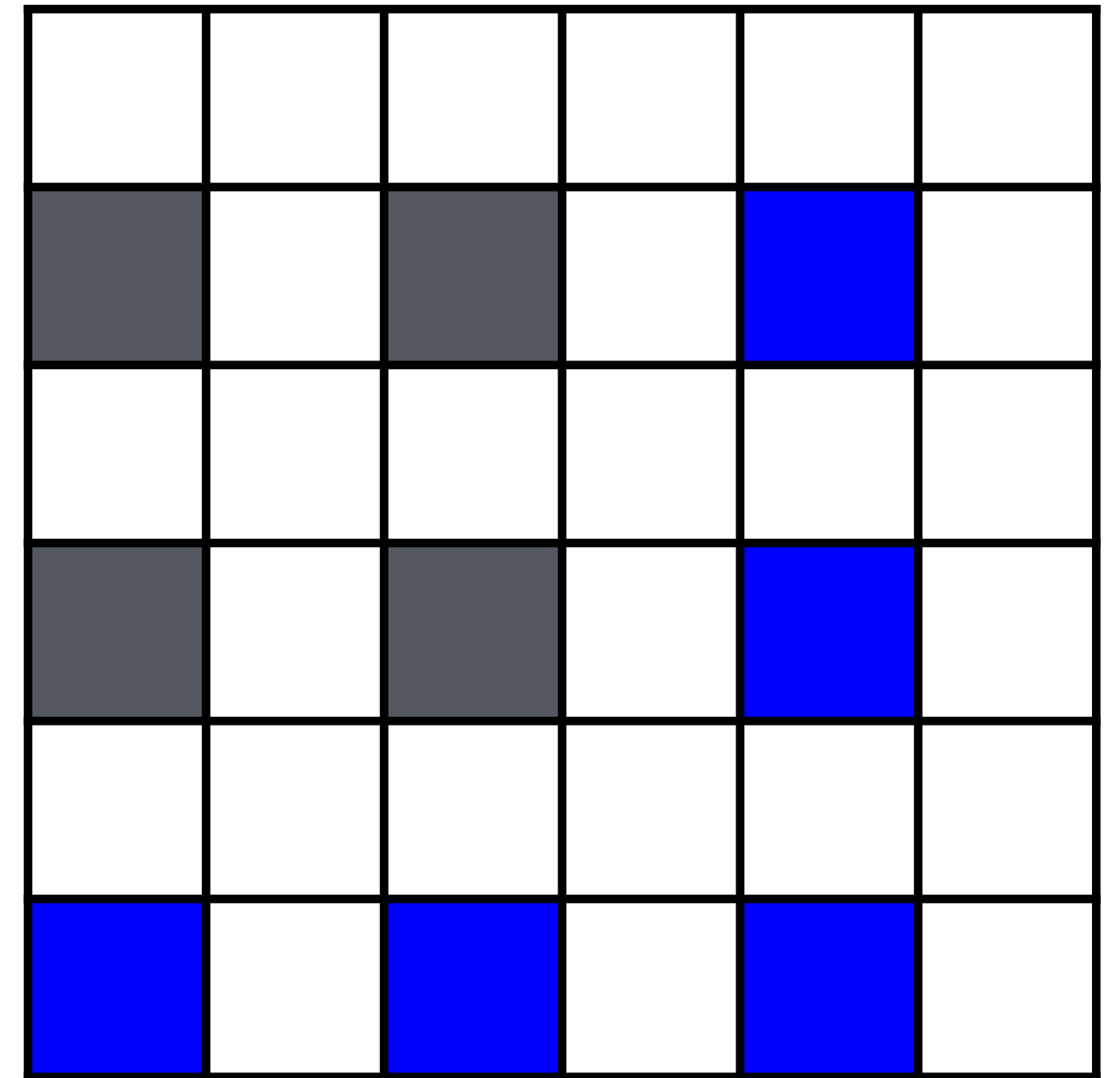
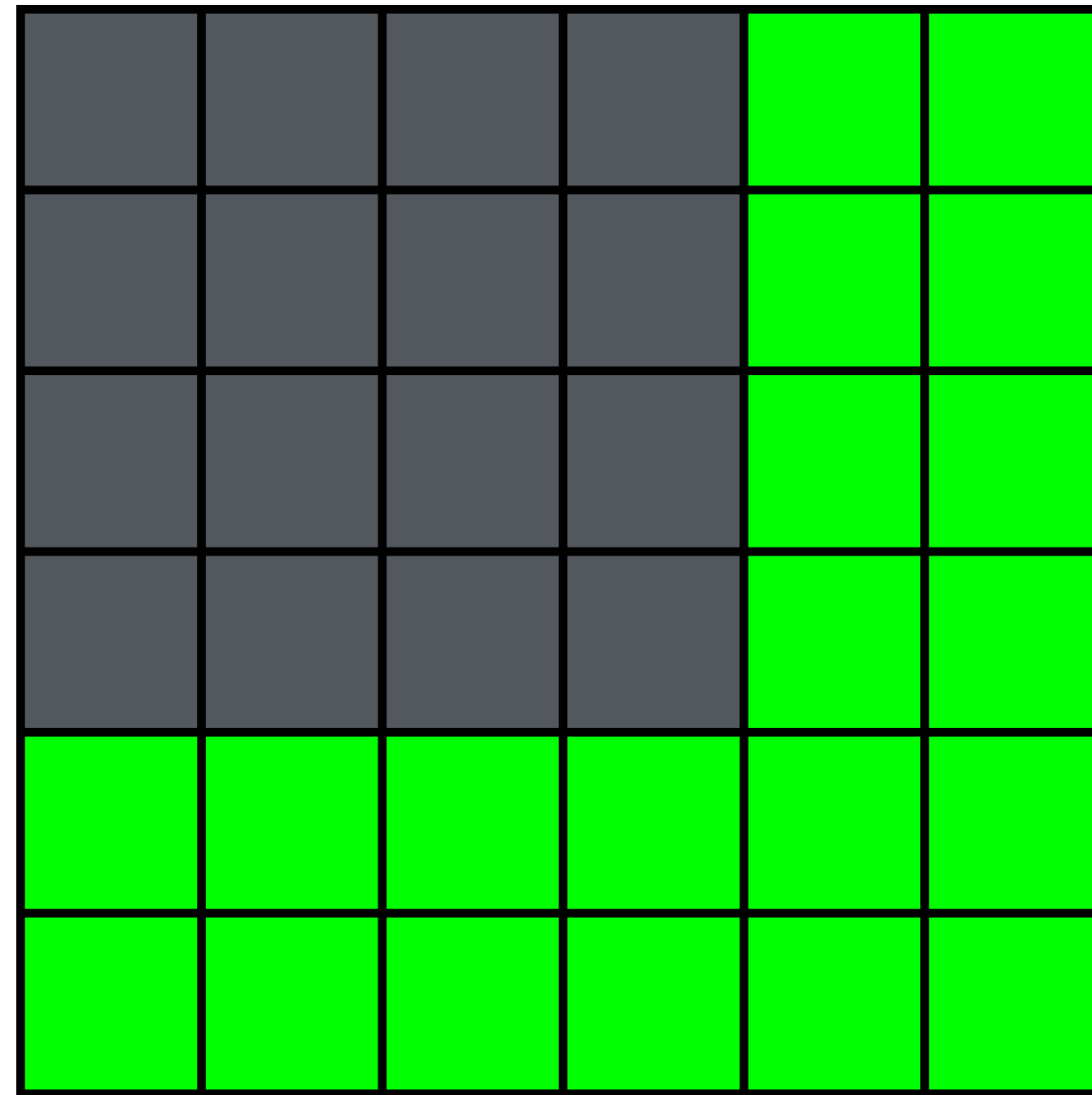
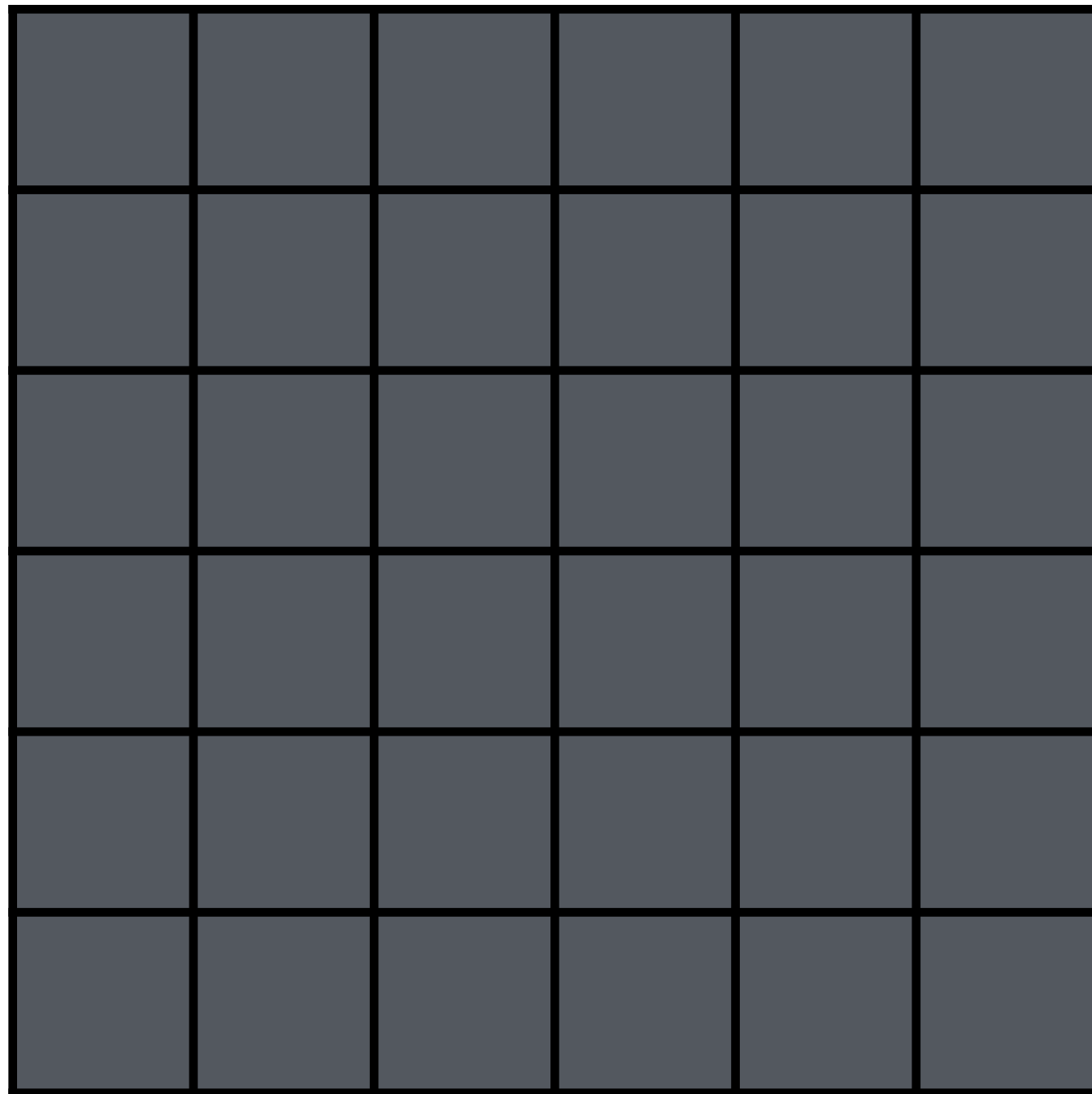
Zero everywhere!



Red-Green difference

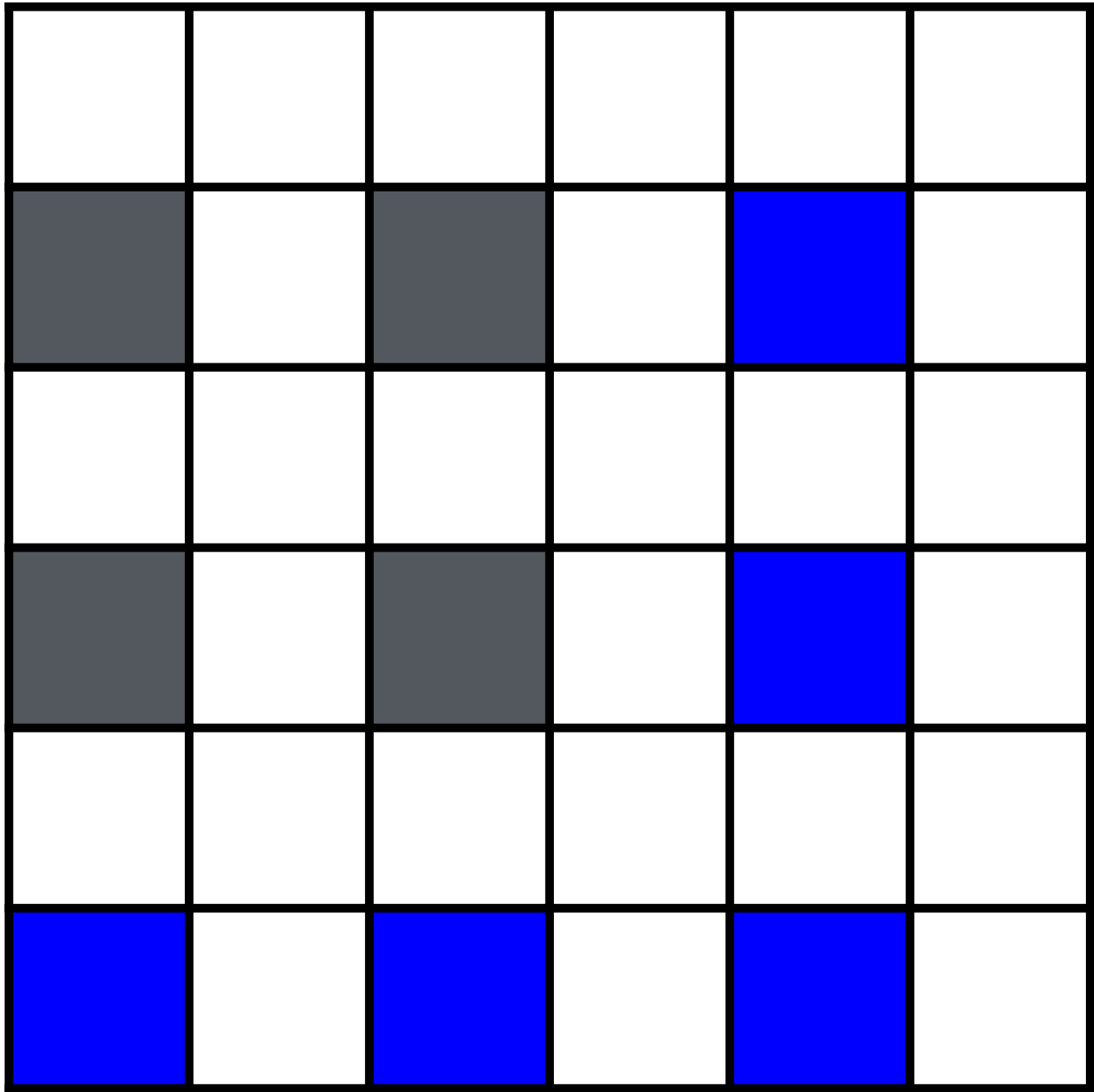
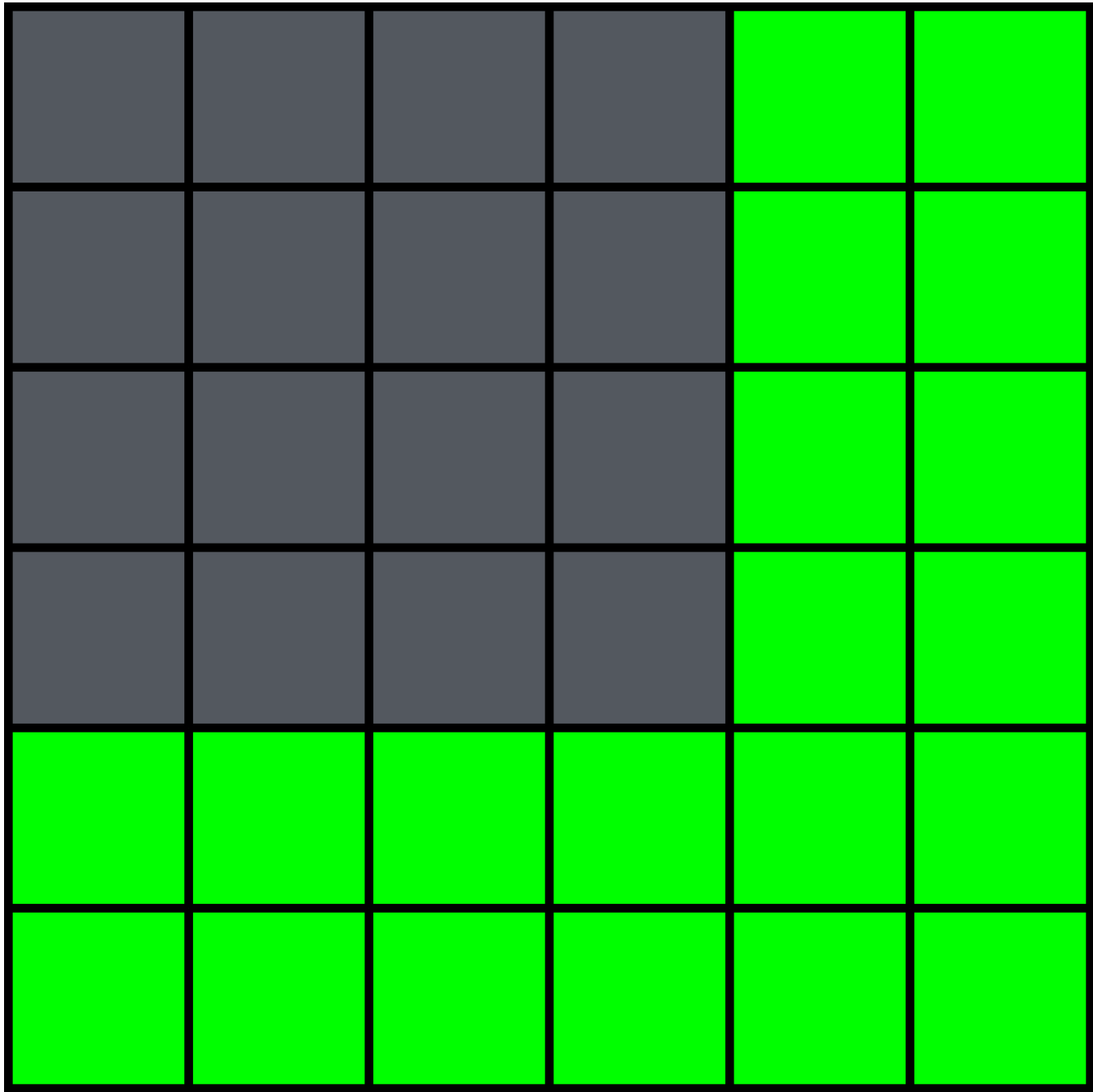
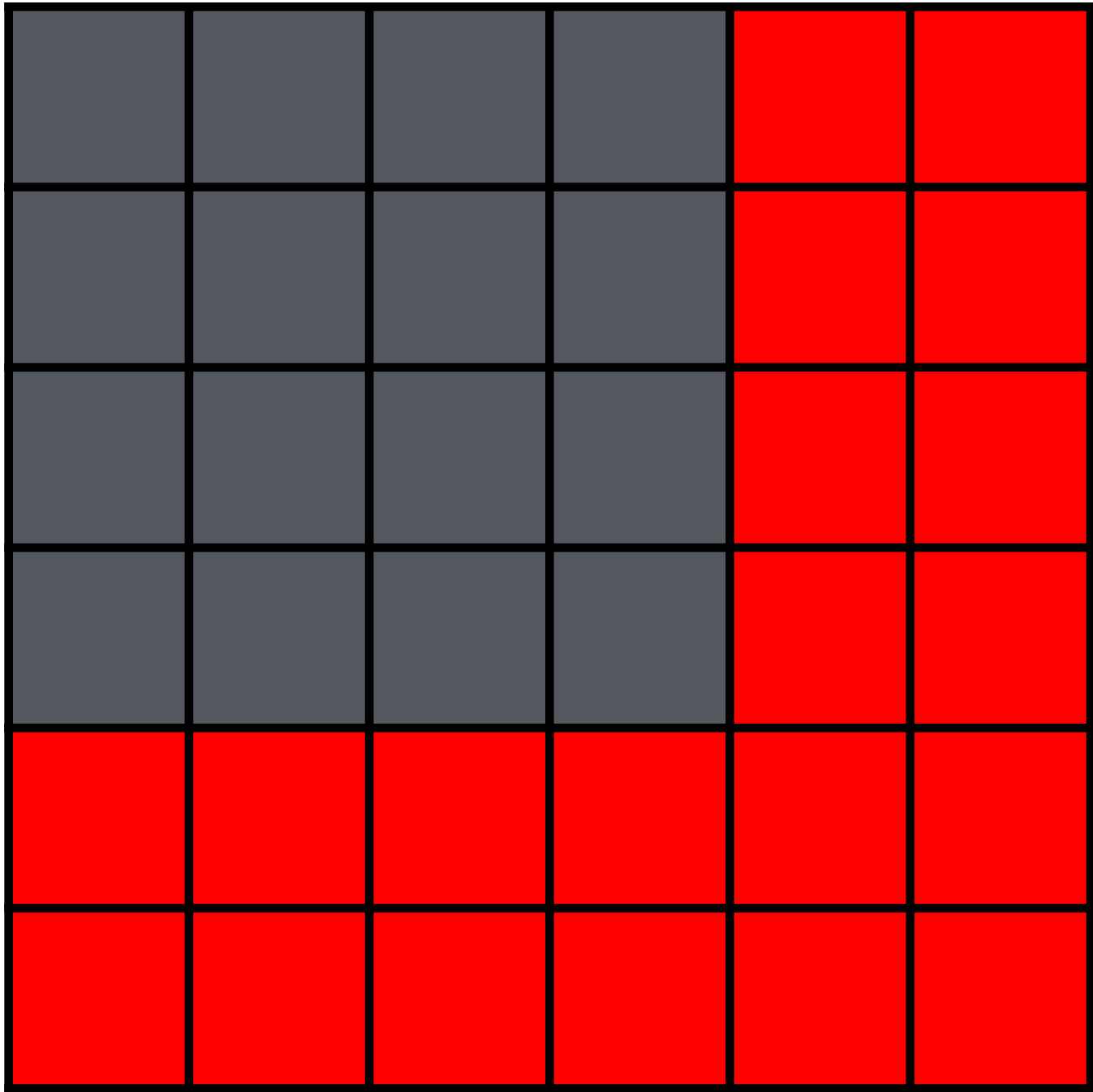
Zero everywhere!

- Easy!



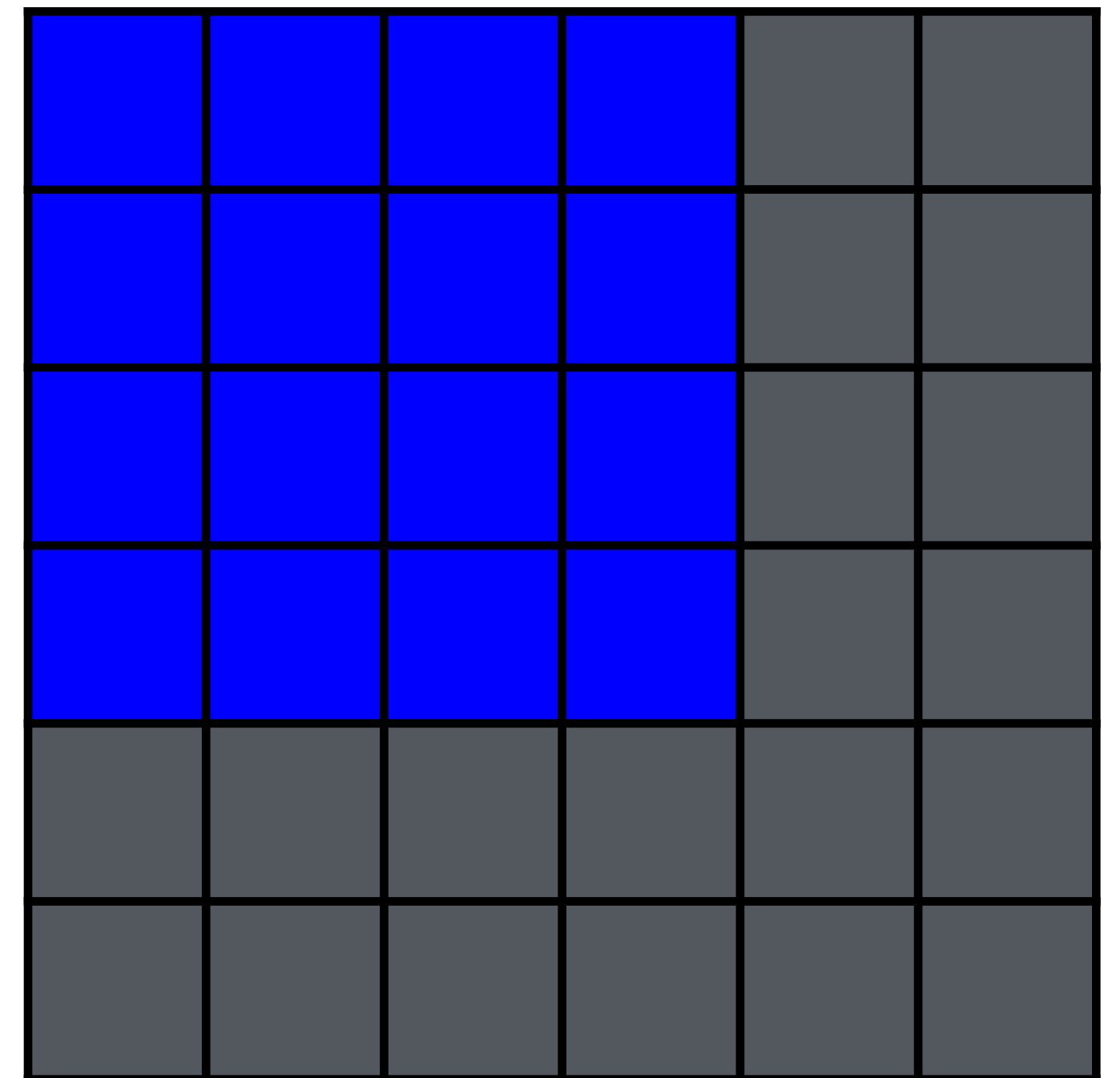
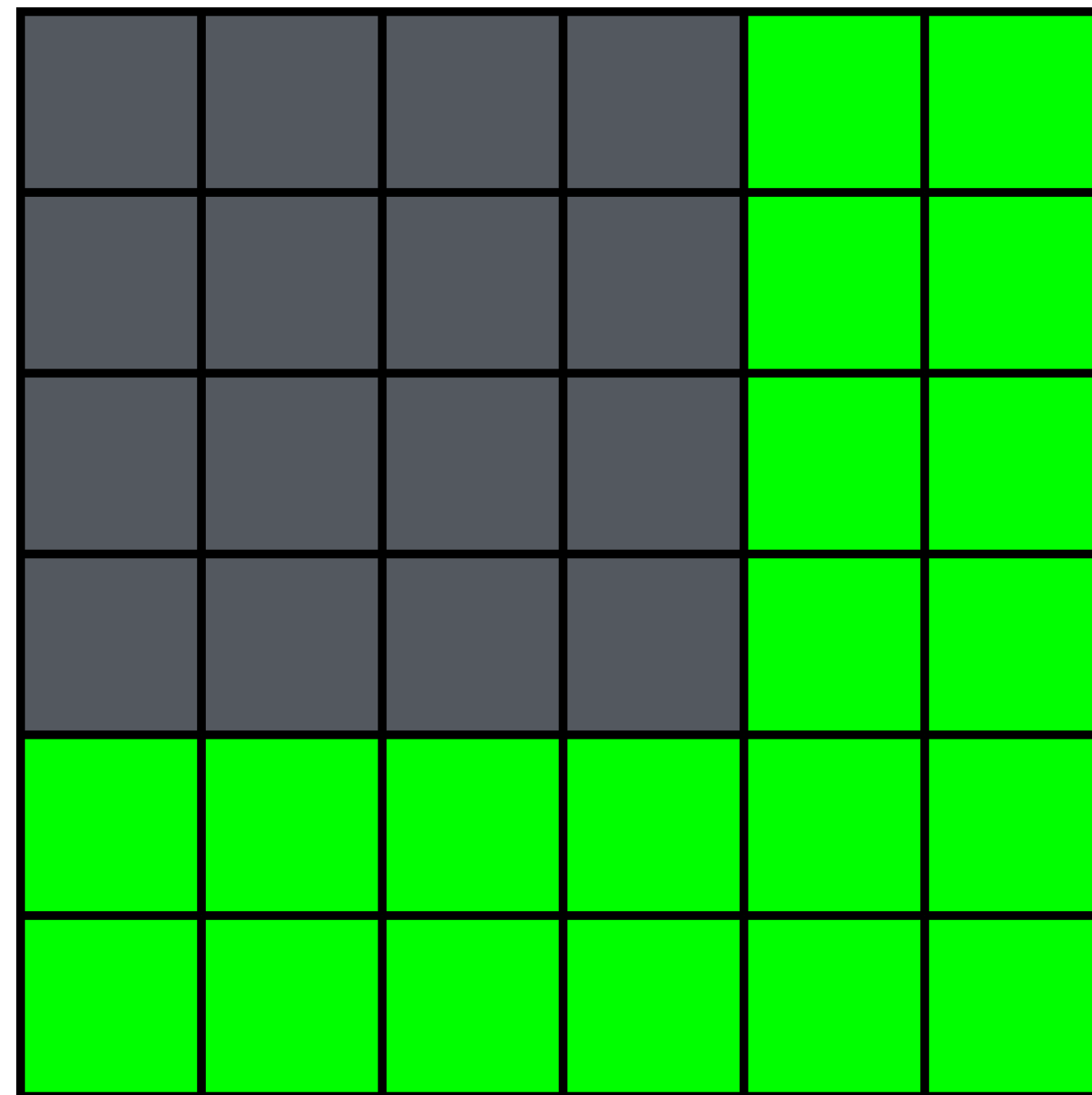
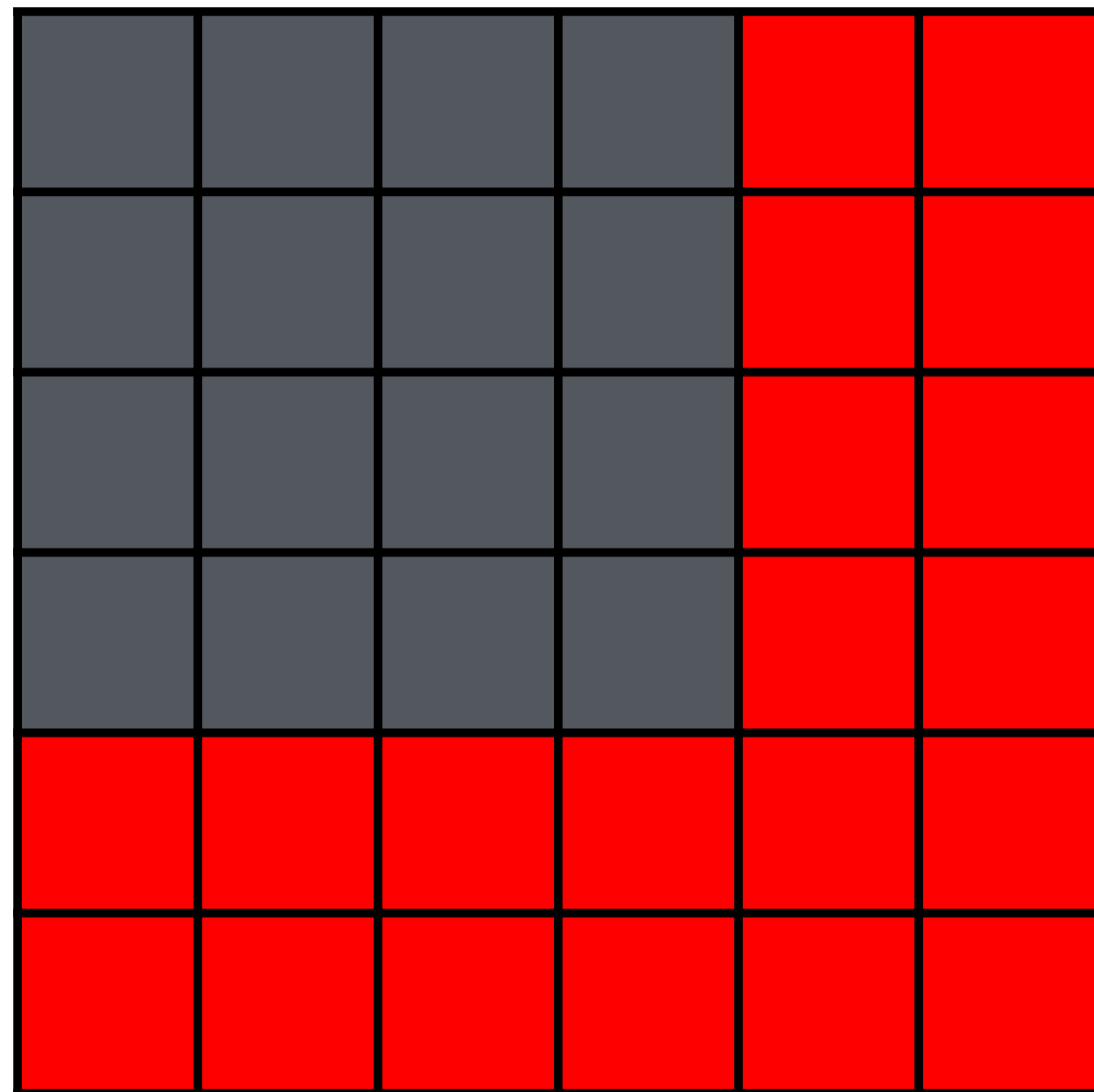


Add back green





Repeat for blue

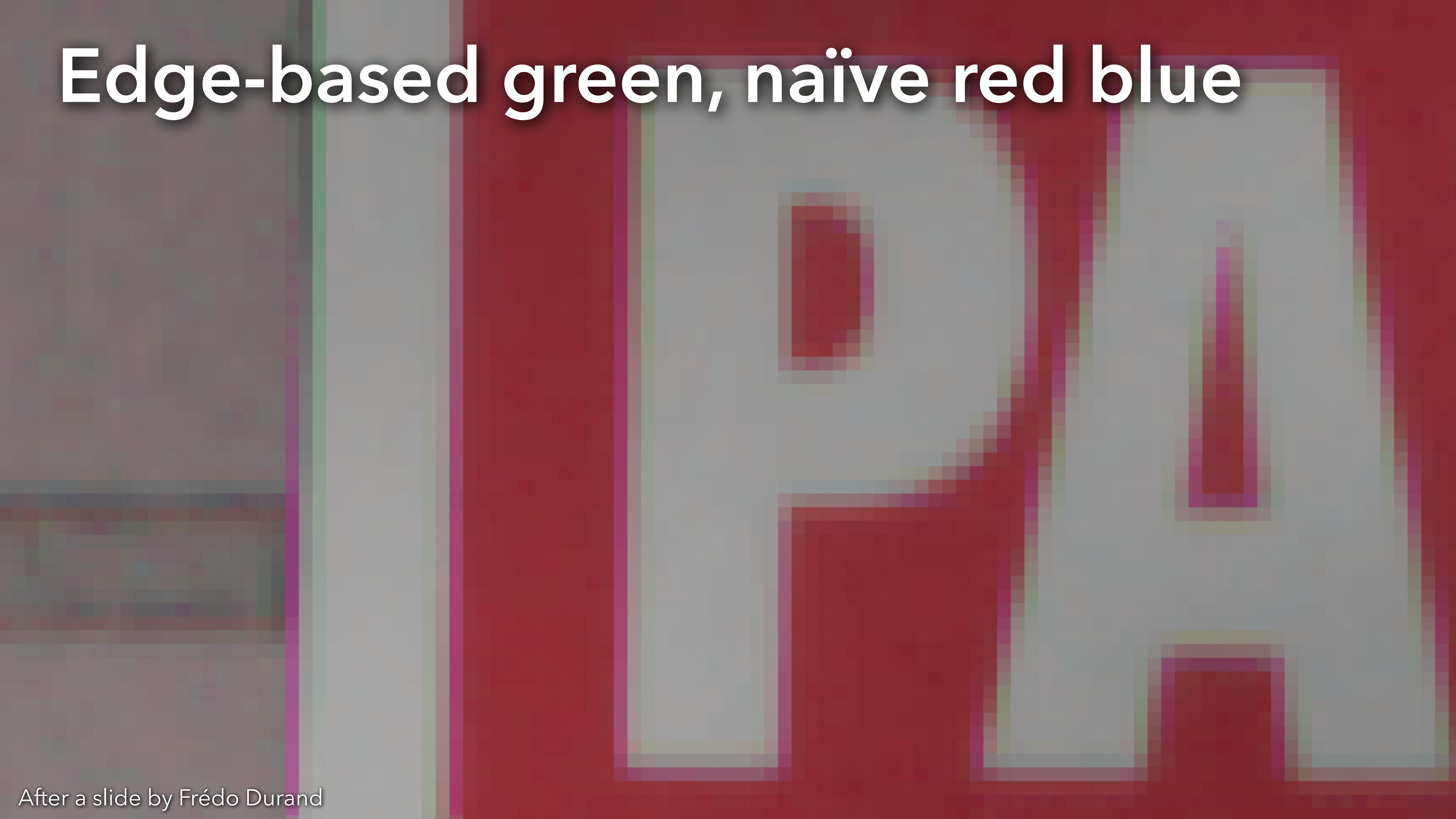


Fully naïve



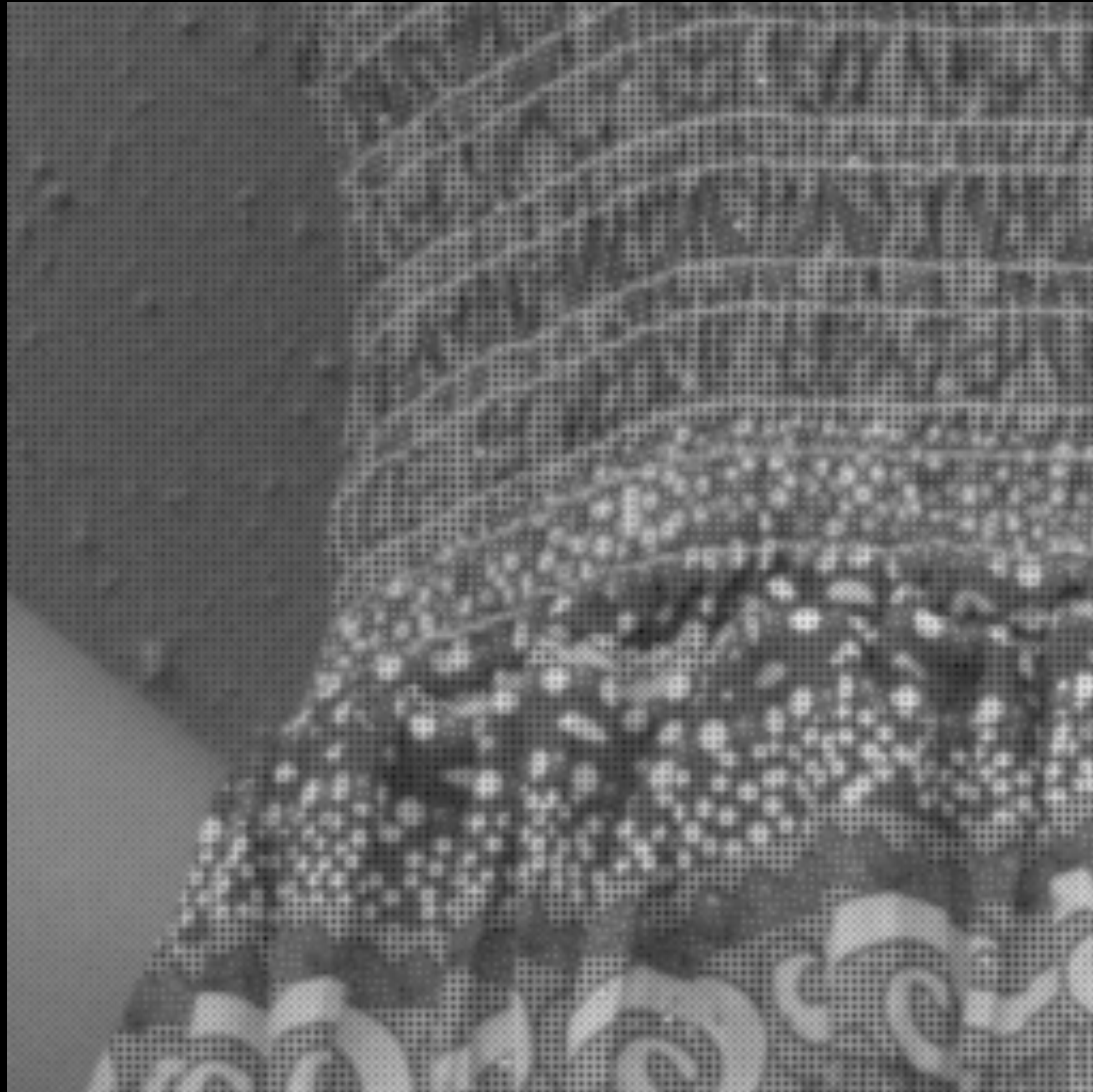
After a slide by Frédo Durand

Edge-based green, naïve red blue



Green-based blue and red

RAW bayer data



After a slide by Steve Marschner

2x2 bayer block



After a slide by Steve Marschner

centered



After a slide by Steve Marschner

linear



After a slide by Steve Marschner

edge-based



After a slide by Steve Marschner